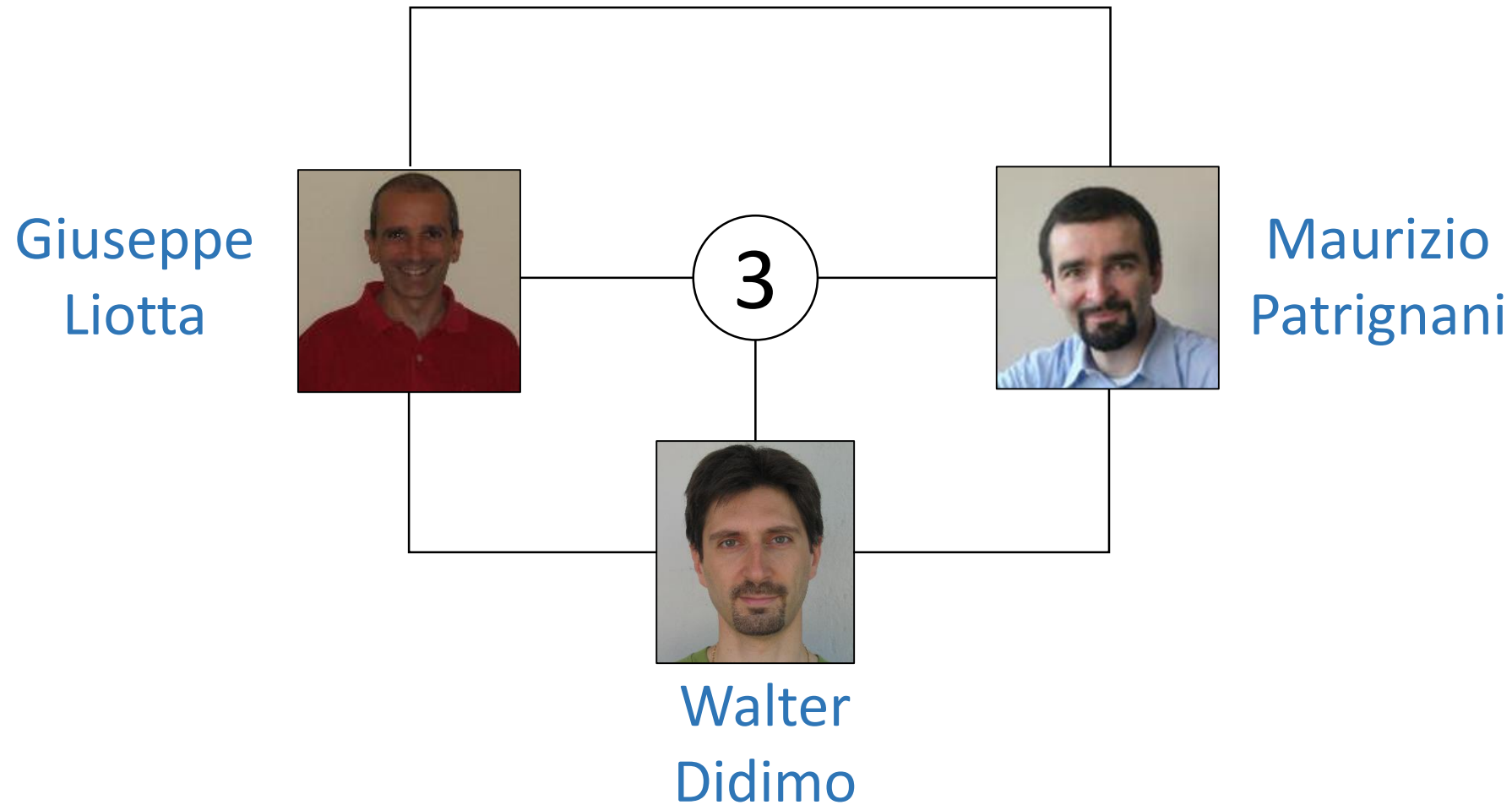
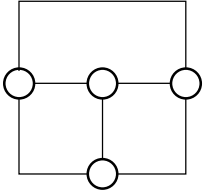


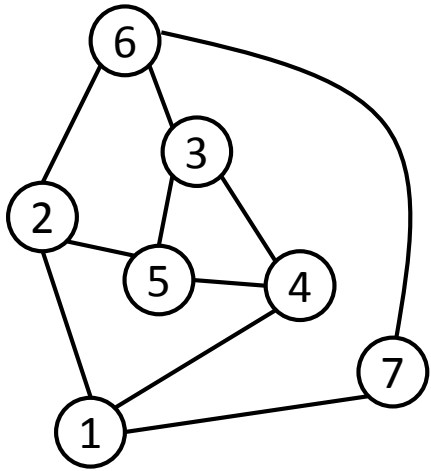
Bend-minimum Orthogonal Drawings in Quadratic Time



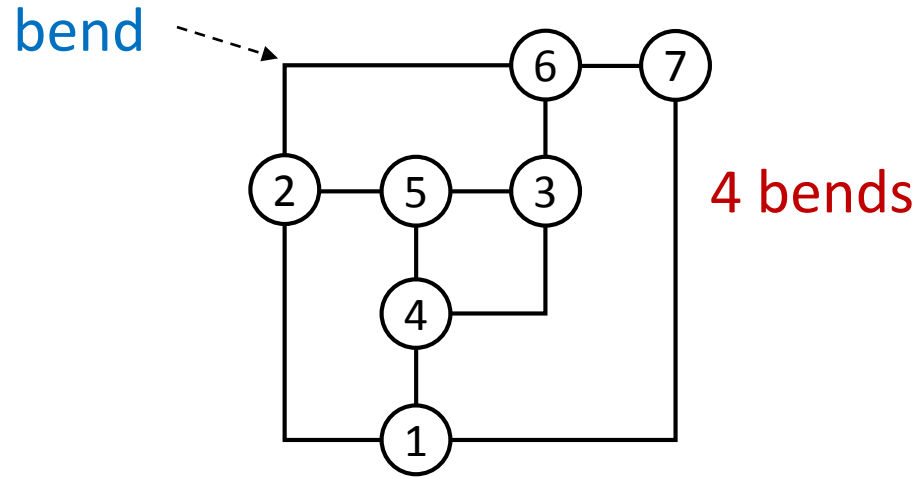


The problem

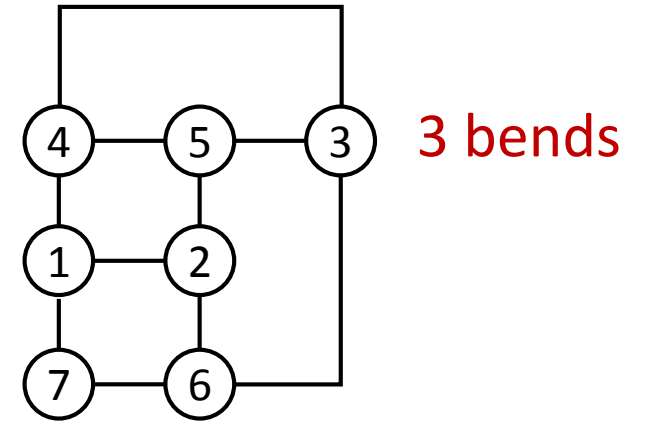
Problem: planar **3-graph** \implies planar **bend-minimum** orthogonal drawing



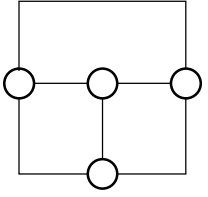
plane 3-graph



bend-min orthogonal drawing
(fixed embedding)



bend-min orthogonal drawing
(variable embedding)



A bit of history

Bend-min orthogonal drawings: **fixed embedding**

- plane 4-graphs

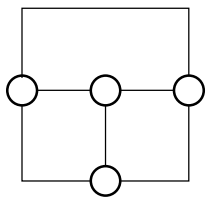
- $O(n^2 \log n)$ [Tamassia (1987)]
- $O(n^{7/4} \sqrt{\log n})$ [Garg and Tamassia (2001)]
- $O(n^{1.5})$ [Cornelsen and Karrenbauer (2011)]

based on
min-cost flow

- plane 3-graphs

- $O(n)$ [Rahman and Nishizeki (2002)]

not based on
flow techniques



A bit of history

Bend-min orthogonal drawings: **variable embedding**

- planar 4-graphs: NP-hard [Garg and Tamassia (2001)]
- planar 3-graphs

1998



$O(n^5 \log n)$

Di Battista-Liotta-
Vargiu

2011



$O(n^{4.5})$

consequence of
Cornelsen-Karrenbauer

2017



$O(n^{2.43} \log^k n)$

Chang and Yen

2018



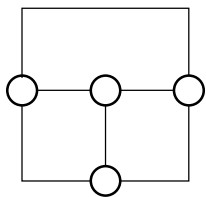
$O(n^2)$

our result

?



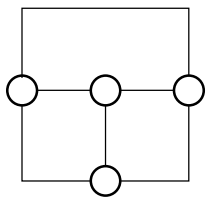
Can we do
better?



Our result

Theorem. Let G be an n -vertex (simple) planar 3-graph. There exists an $O(n^2)$ -time algorithm that computes a bend-minimum orthogonal drawing of G , with at most two bends per edge.

P. S. the algorithm takes $O(n)$ time if we require that a prescribed edge of G is on the external face



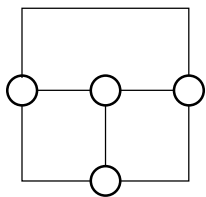
General strategy for biconnected graphs

input: G biconnected planar 3-graph with n vertices

output: bend-min orthogonal drawing Γ of G

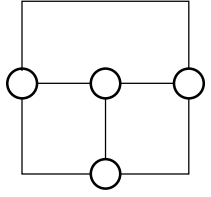
- for each edge e of G
 - $\Gamma_e \leftarrow$ min-bend orthogonal drawing of G with e on the external face
- return $\Gamma \leftarrow$ min-bends $\{\Gamma_e\}$

Γ_e is computed in linear time

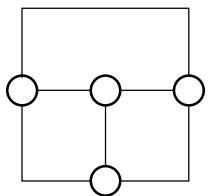


Strategy for the linear-time algorithm

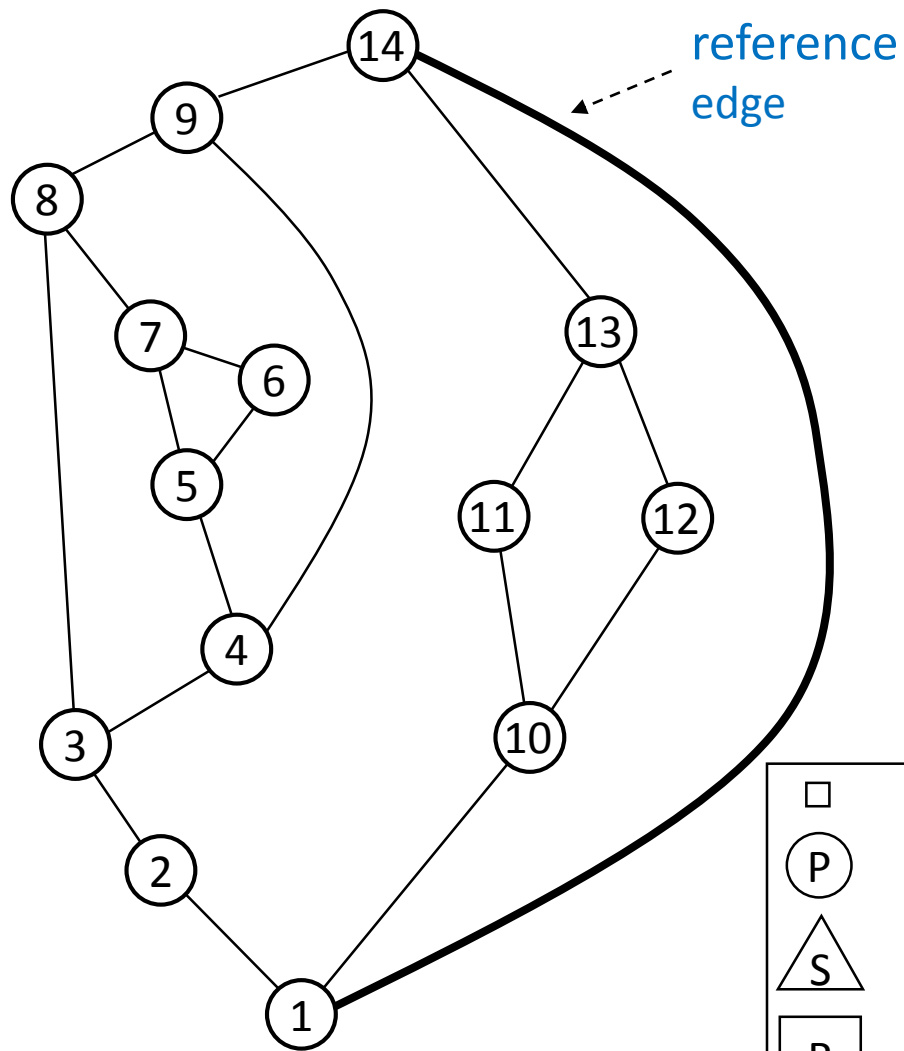
- Incremental construction of Γ_e
 1. bottom-up visit of the SPQR-tree + *orthogonal spirality* (similar to Di Battista, Liotta, Vargiu 1998)
 2. new properties of bend-min orthogonal drawings of planar 3-graphs
 3. non-flow based computation of bend-min orthogonal drawings for the rigid components



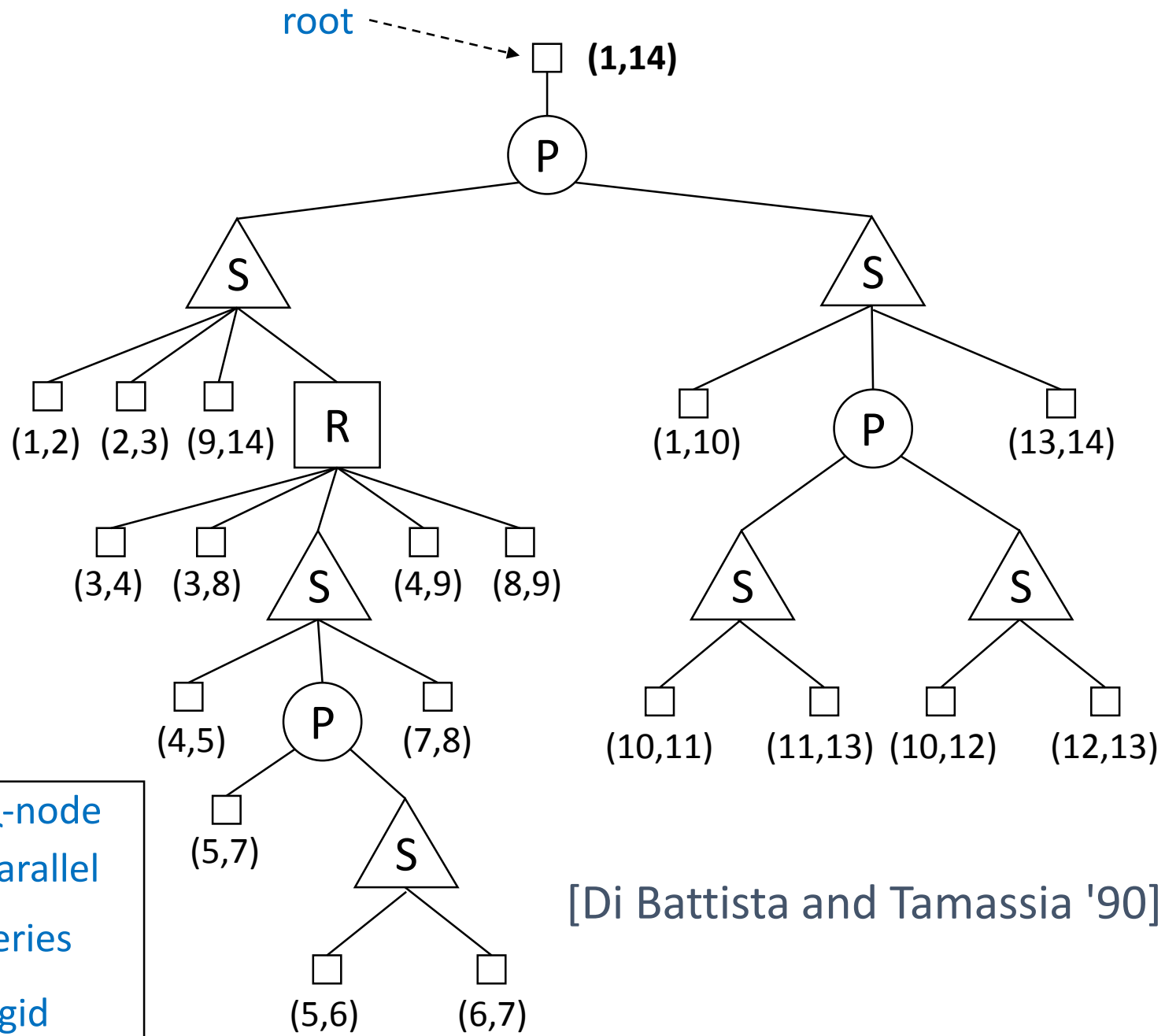
`\begin{SPQR-trees}`



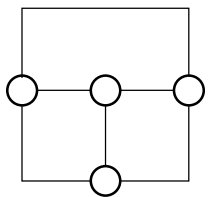
SPQR-trees



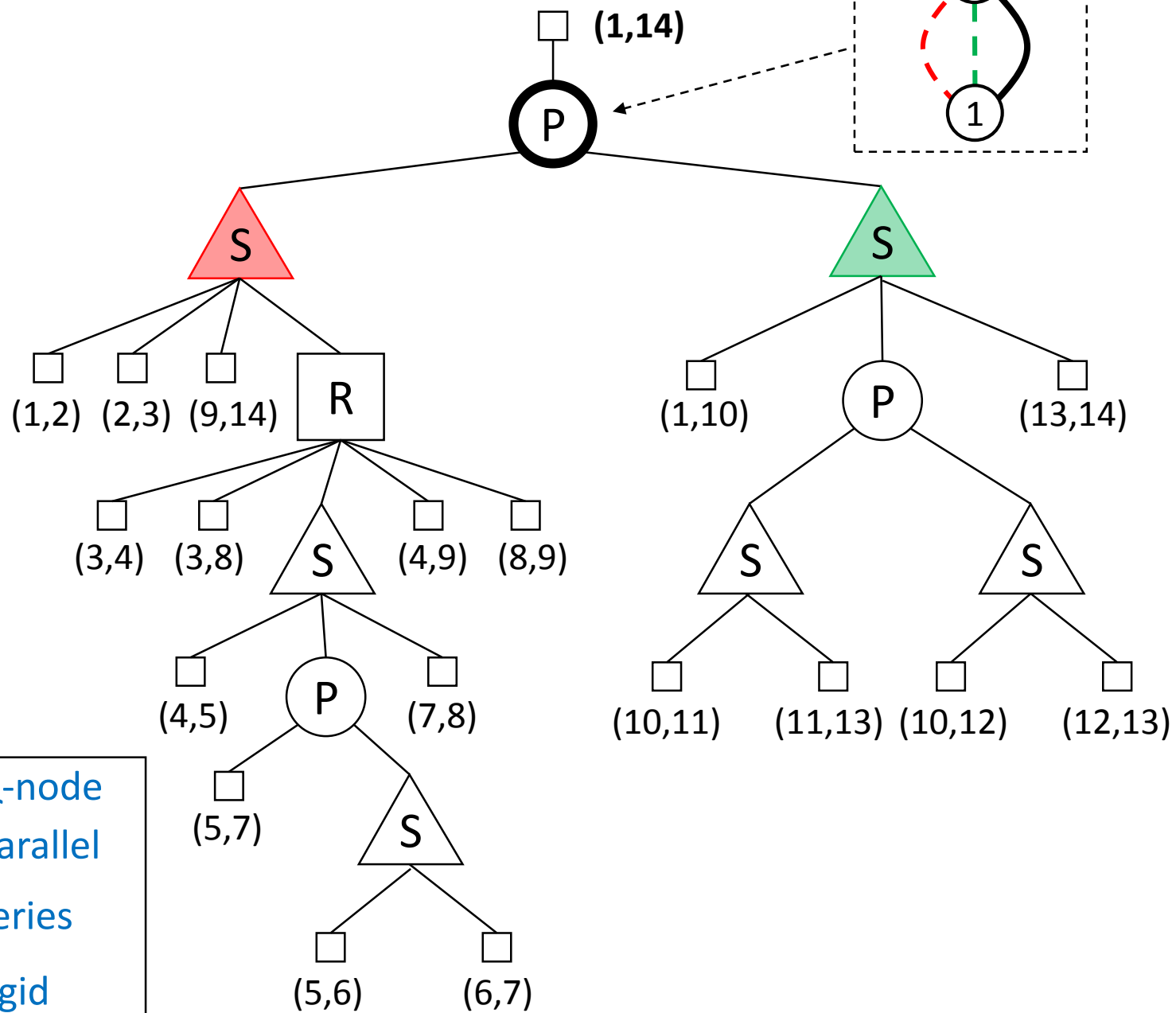
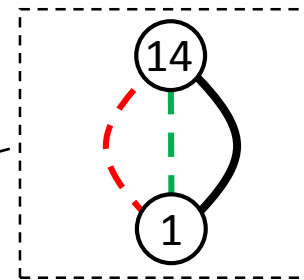
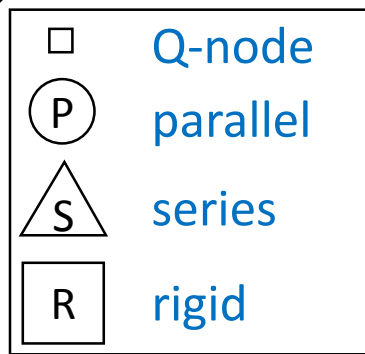
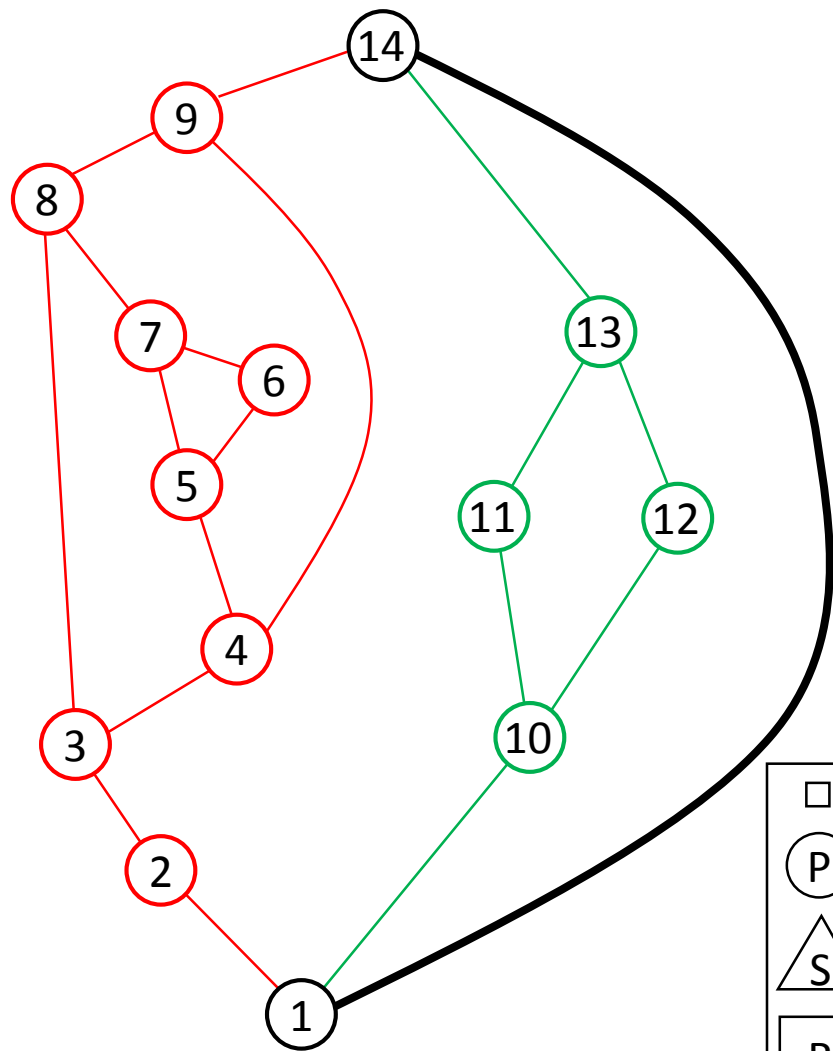
□	Q-node
⊙	parallel
△	series
▣	rigid

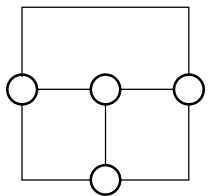


[Di Battista and Tamassia '90]

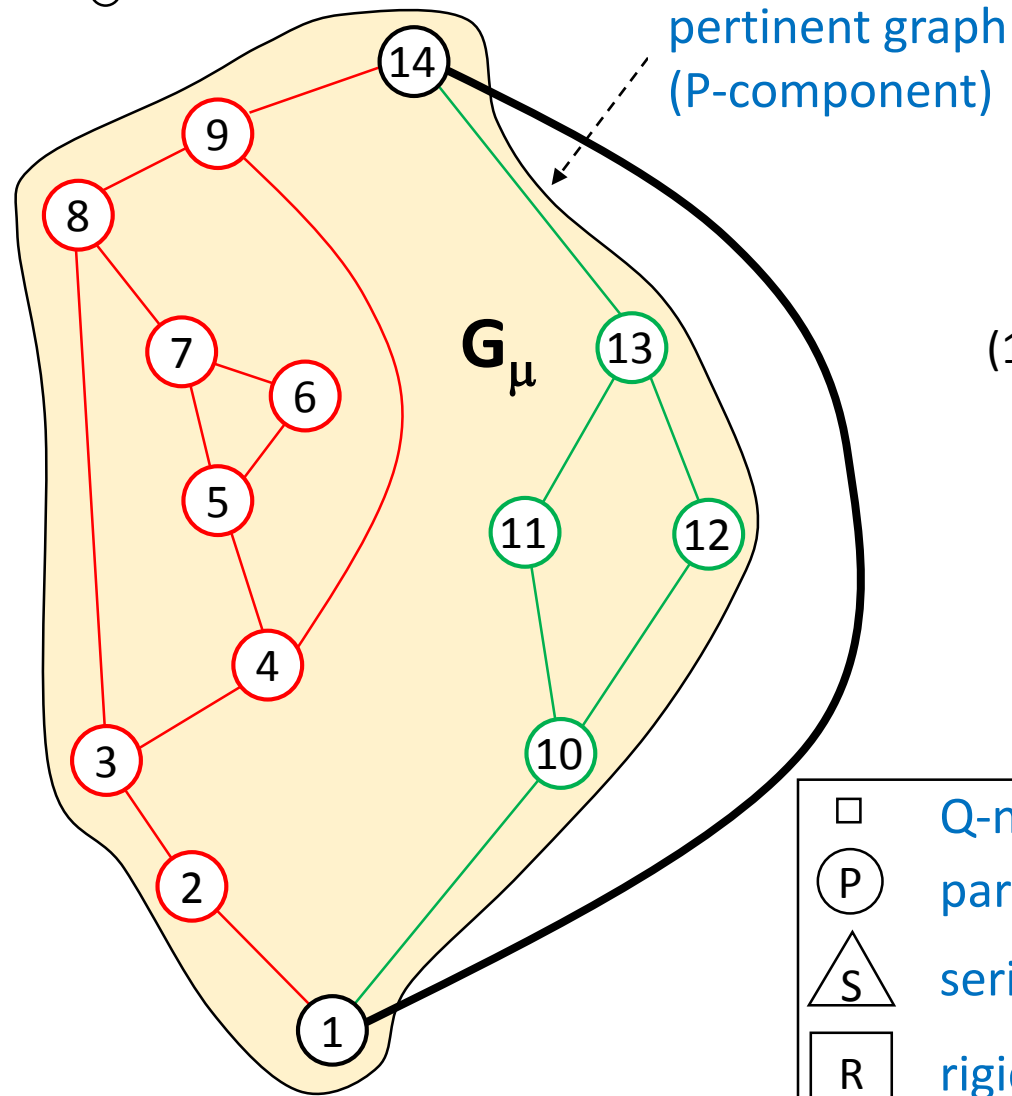


SPQR-trees

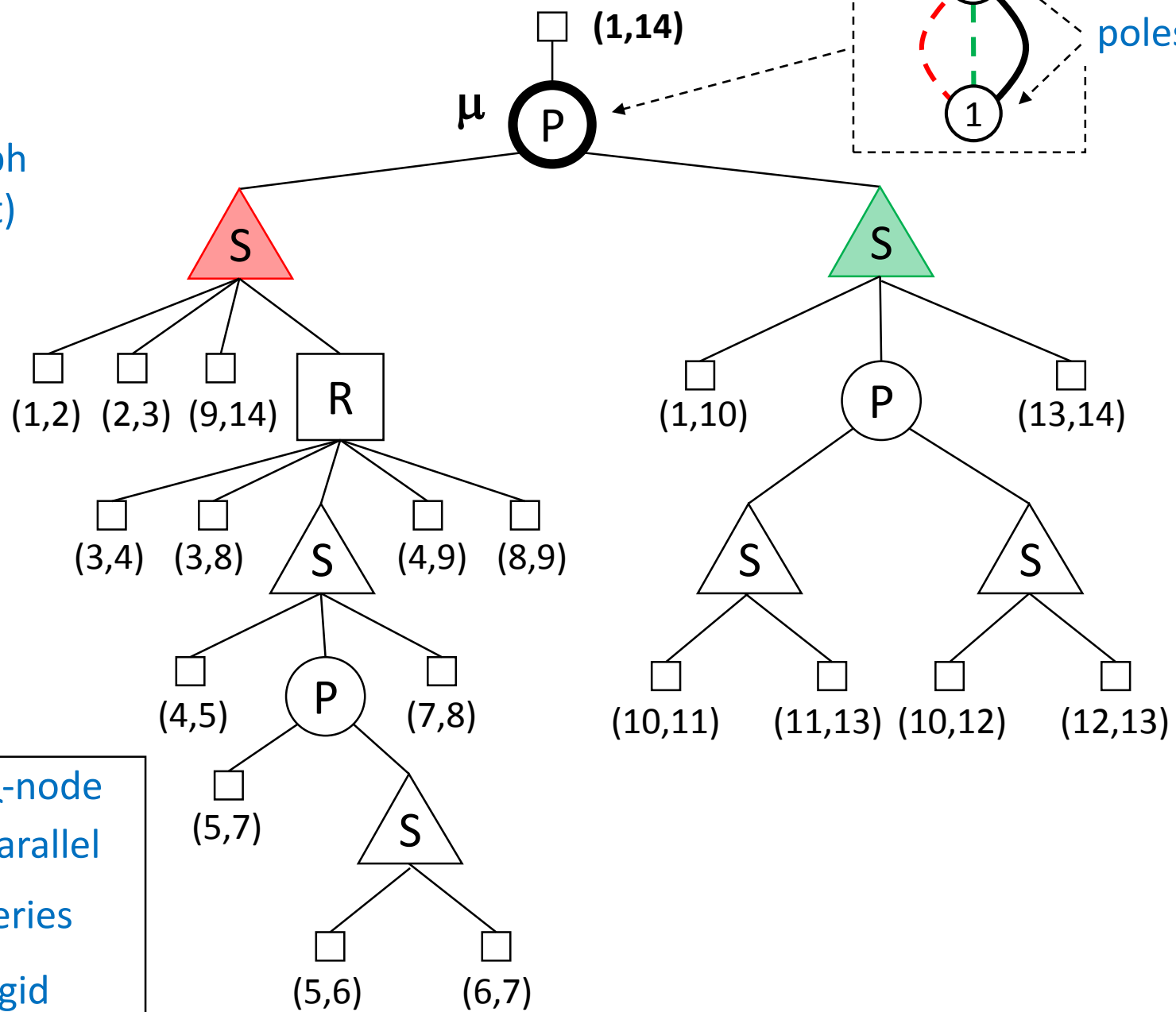
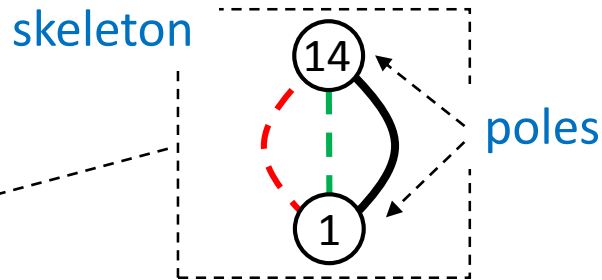


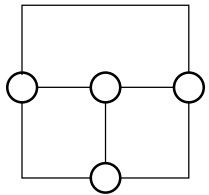


SPQR-trees

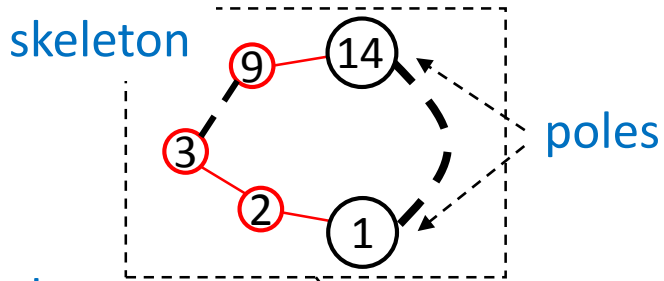
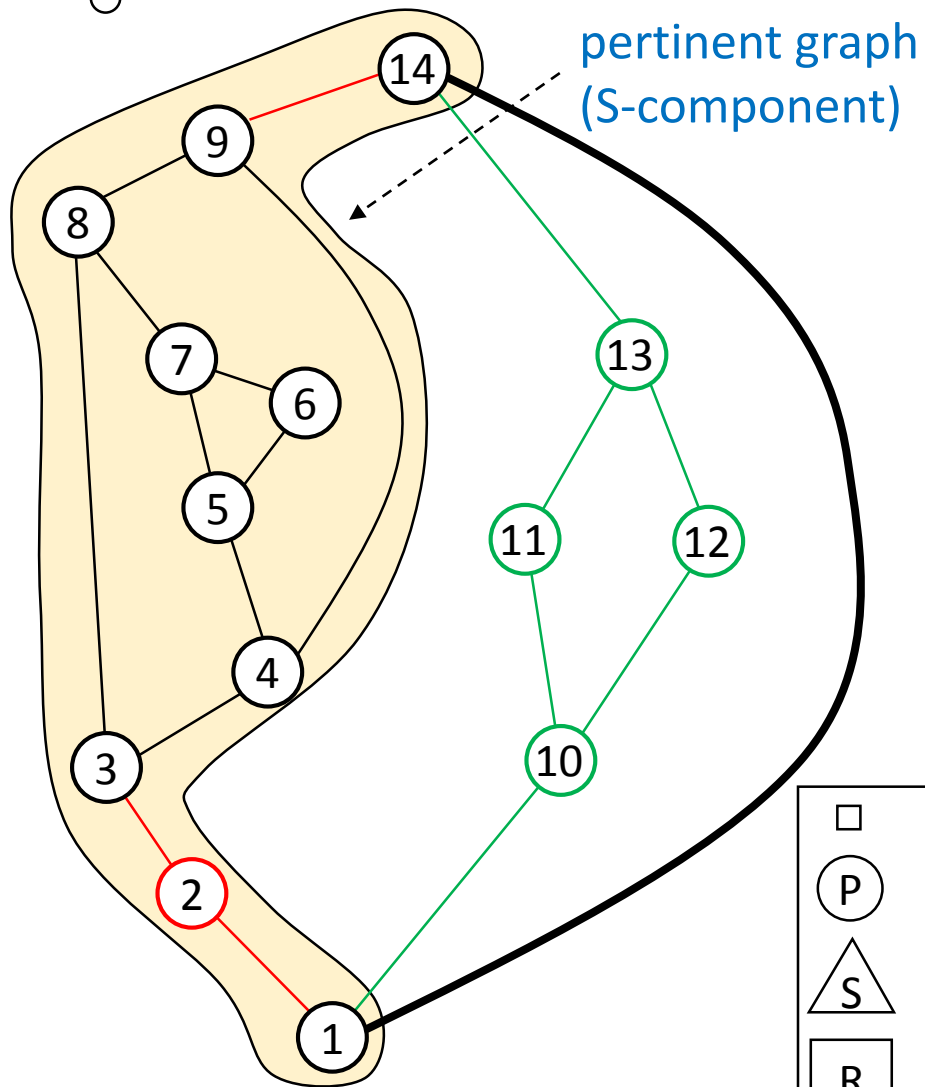


□	Q-node
⊙	parallel
△	series
□	rigid

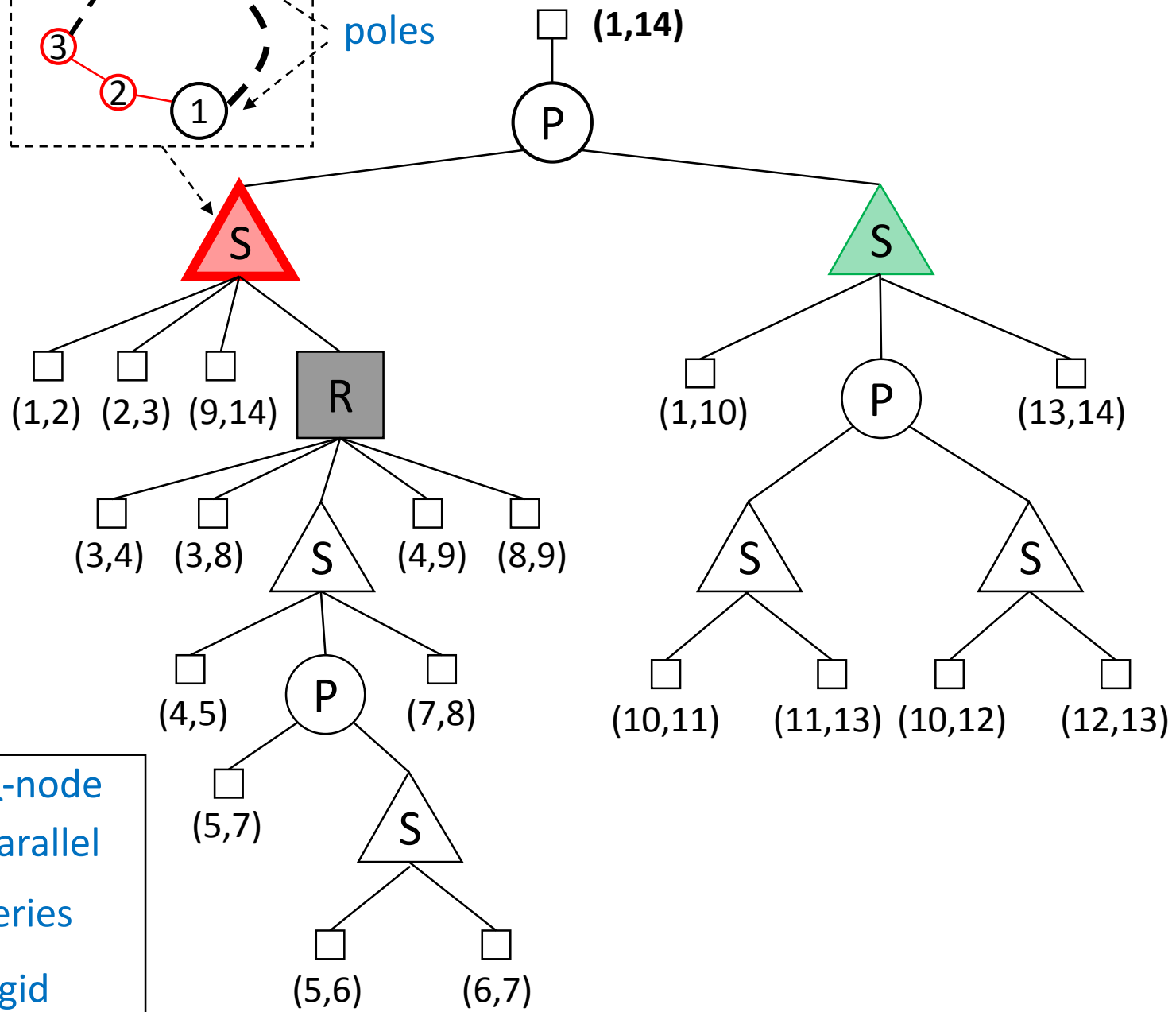


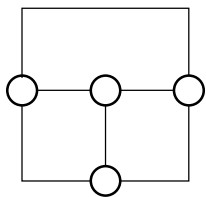


SPQR-trees

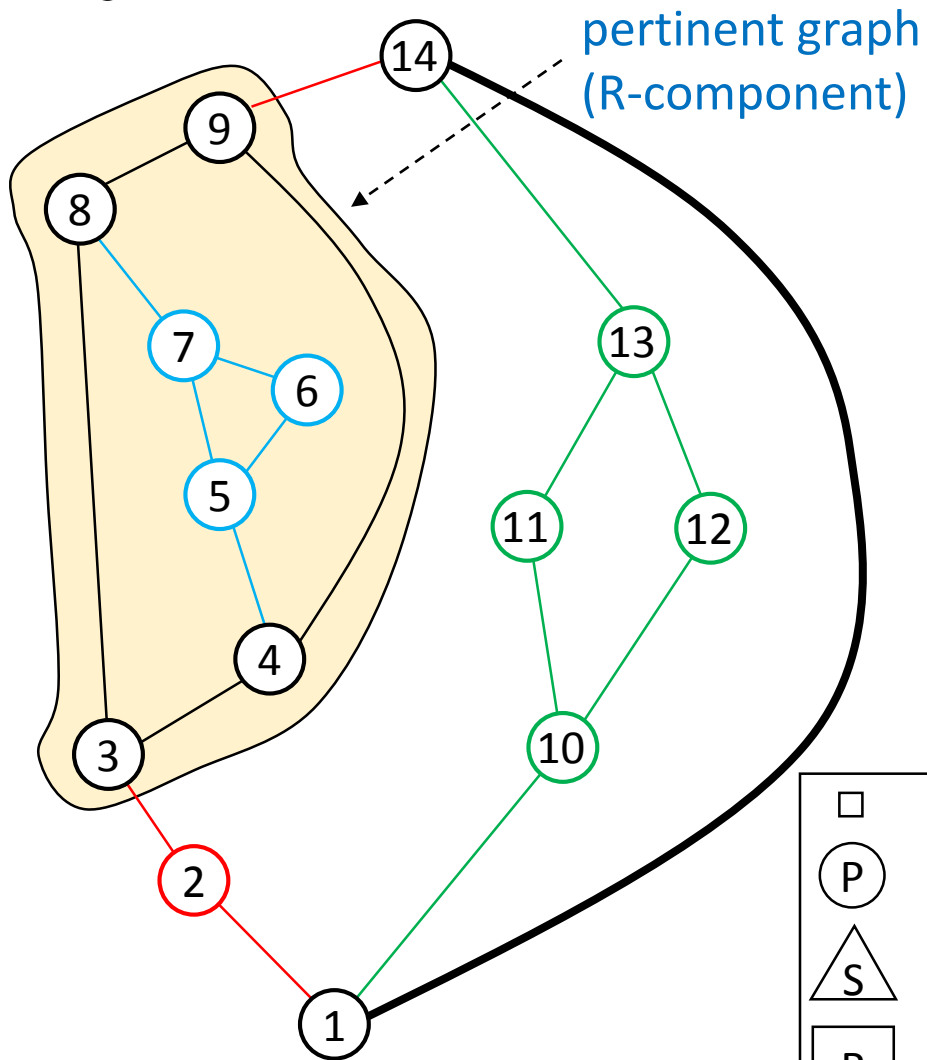


□	Q-node
⊙	parallel
△	series
■	rigid



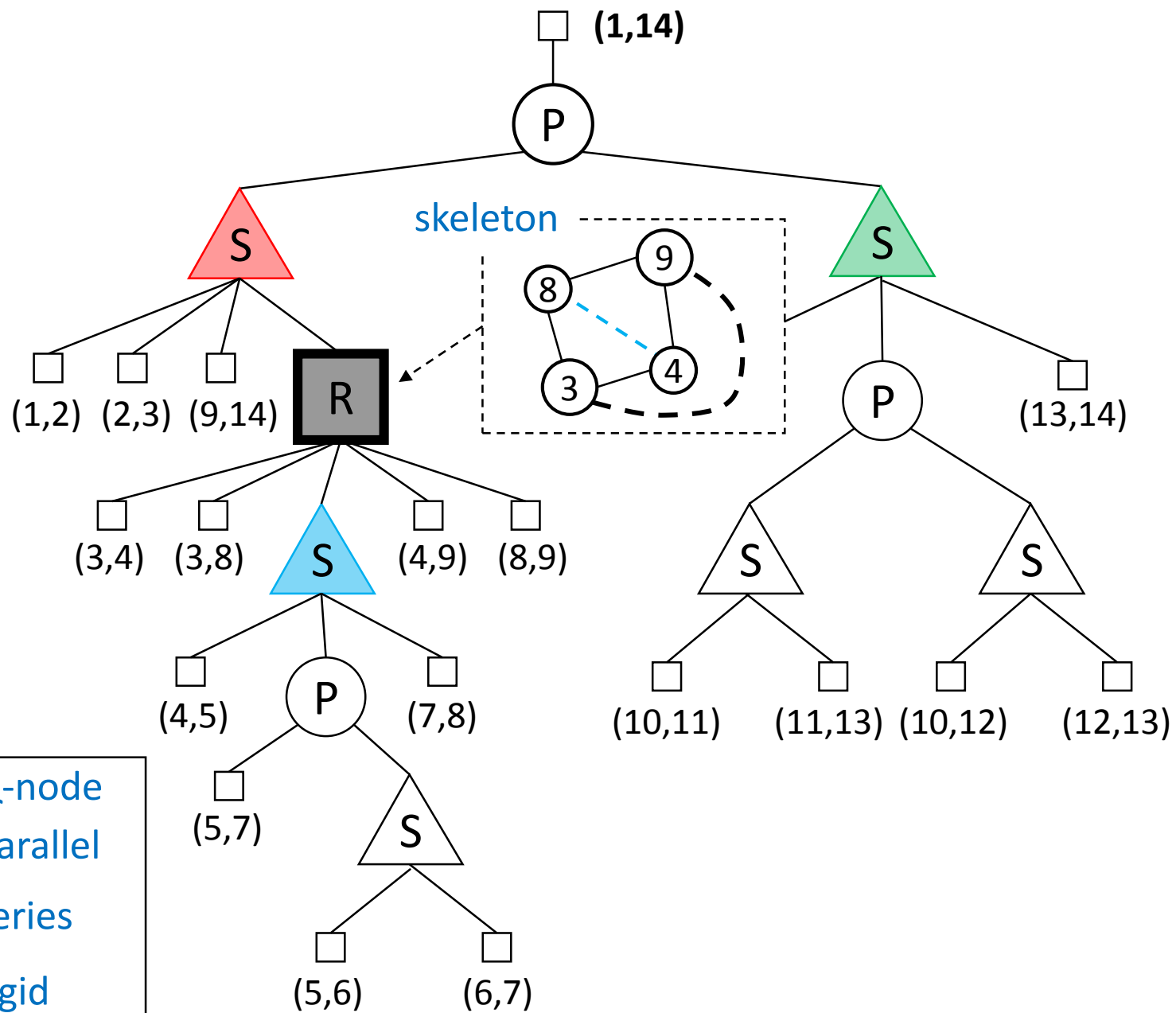


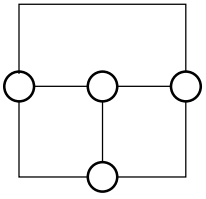
SPQR-trees



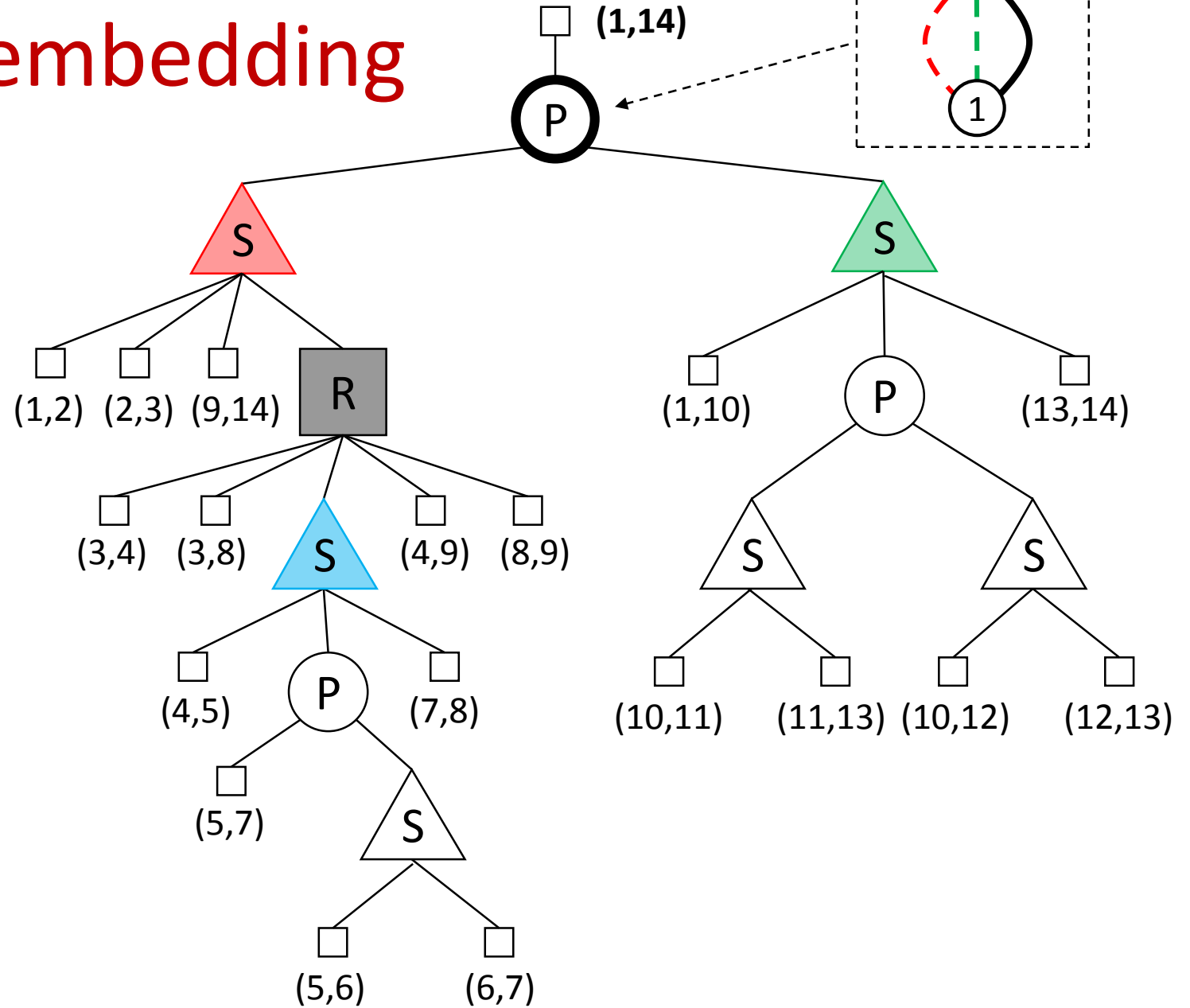
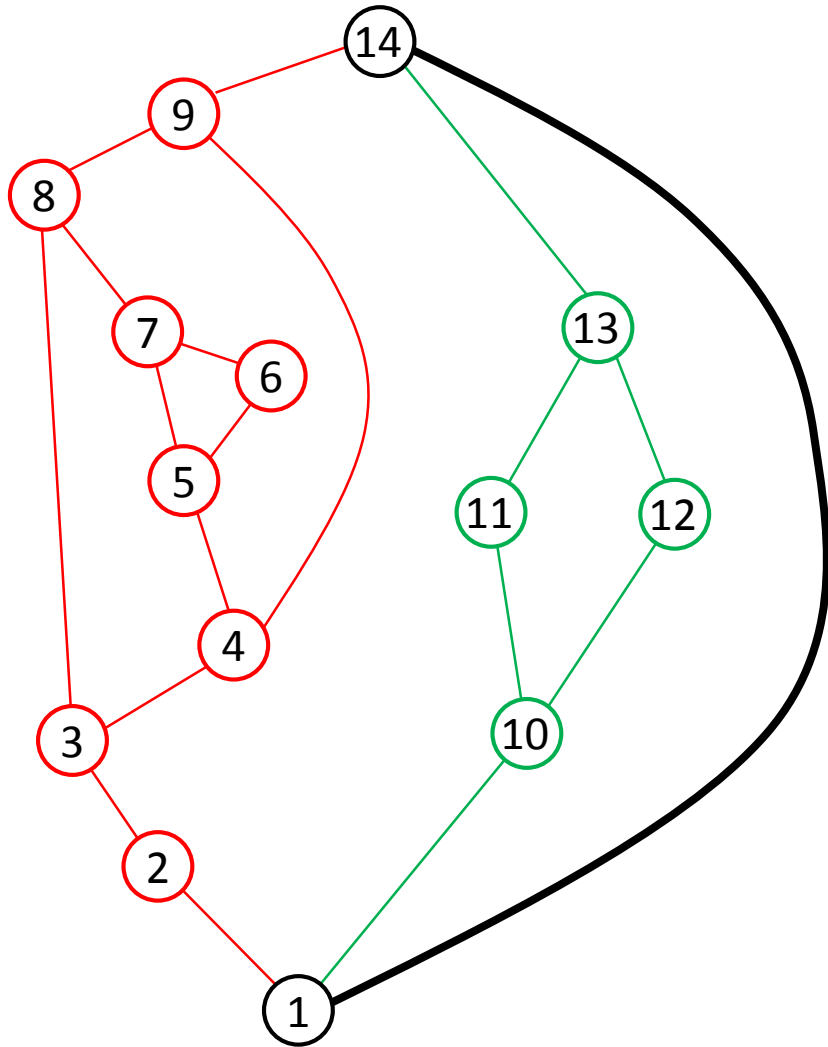
pertinent graph
(R-component)

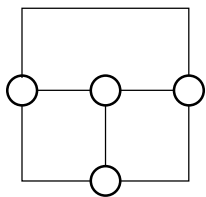
□	Q-node
⊖	parallel
△	series
■	rigid



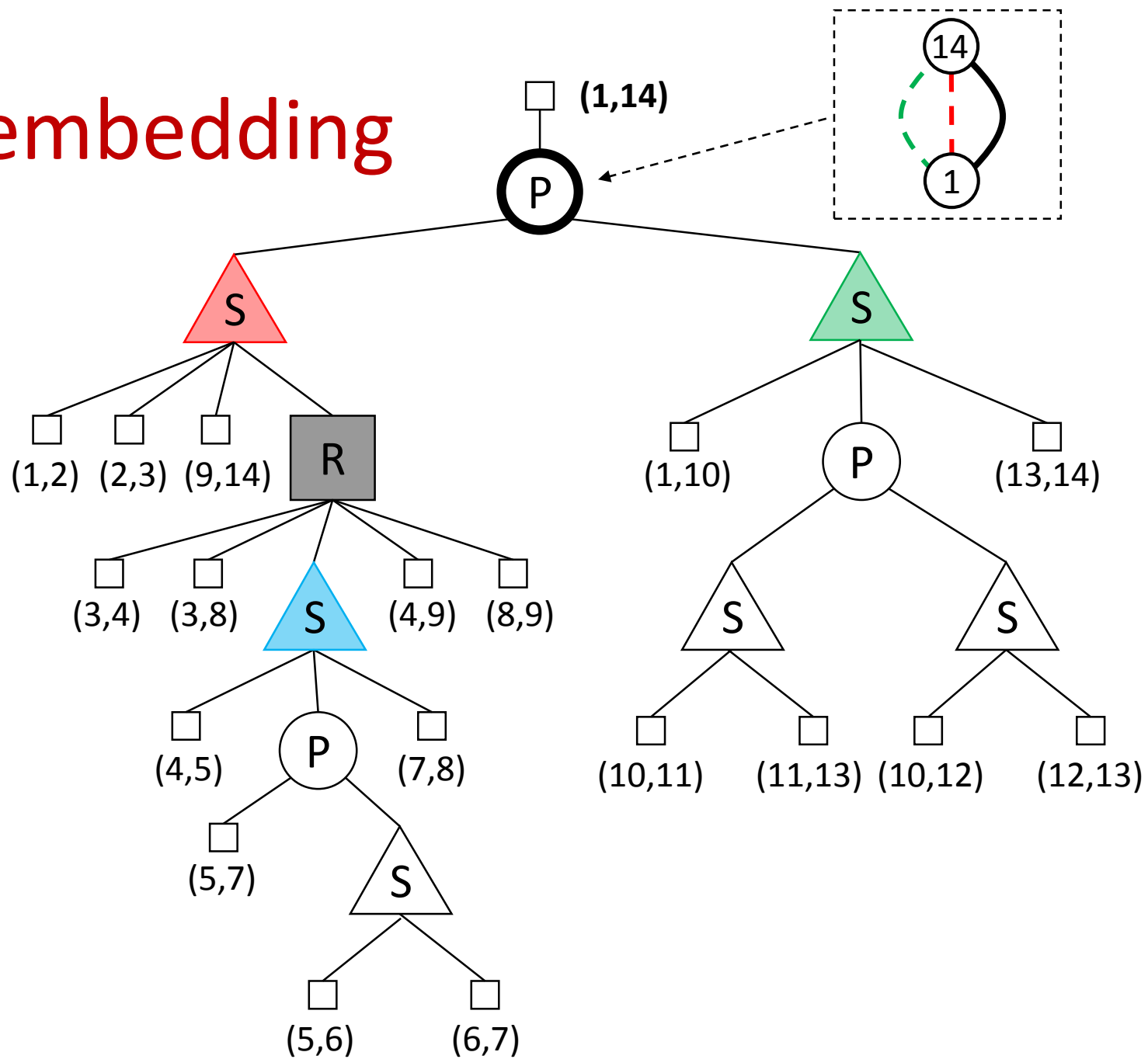
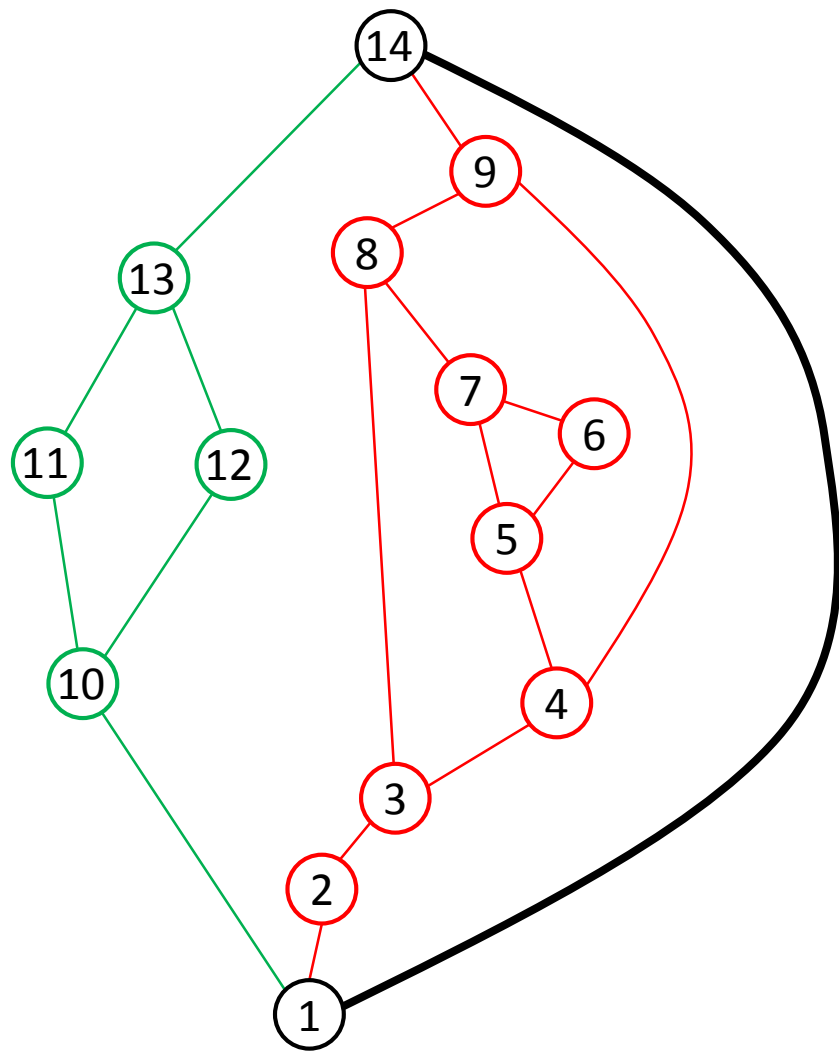


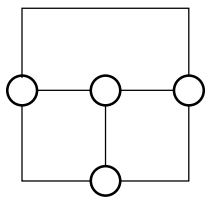
Changing the embedding



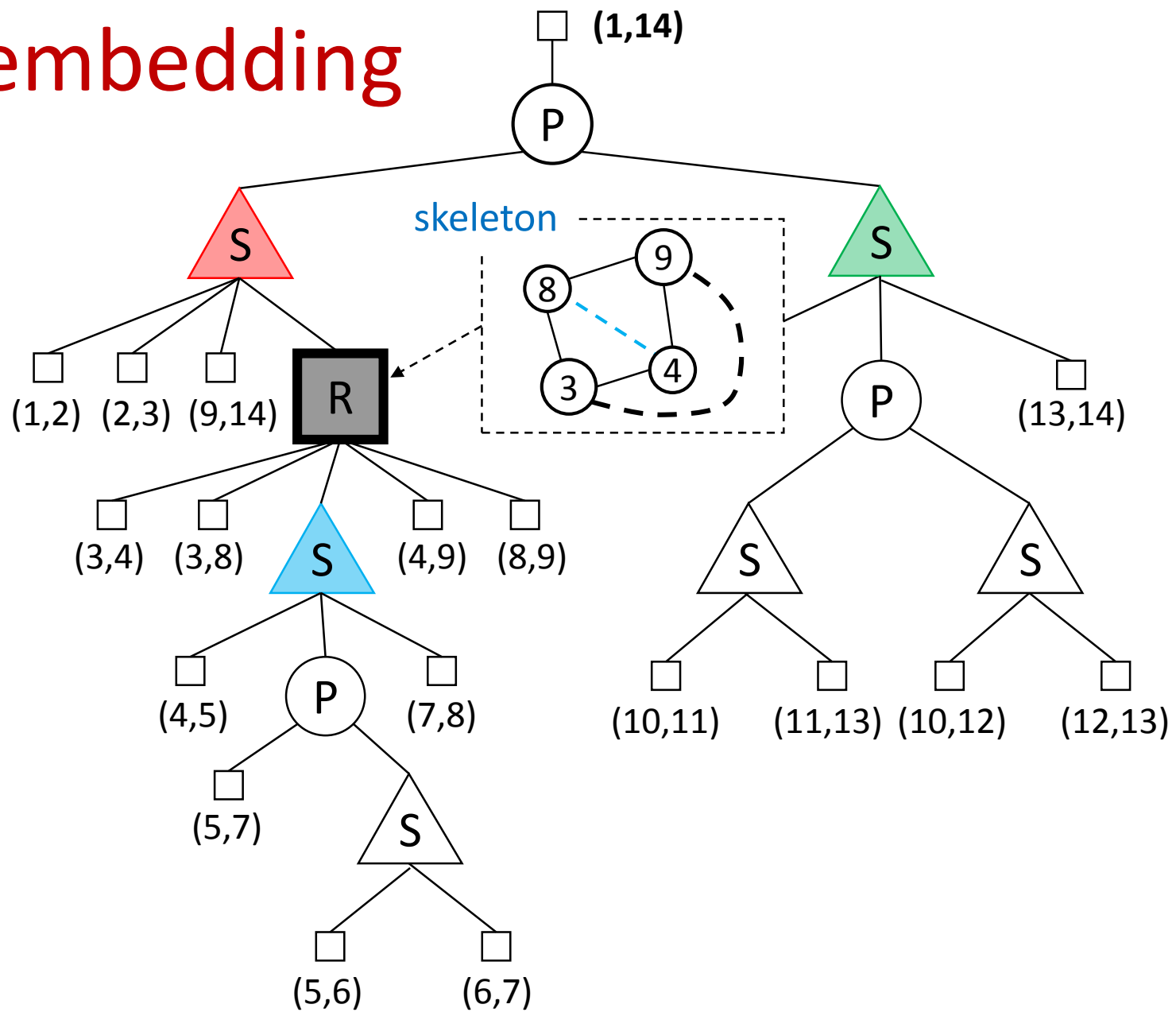
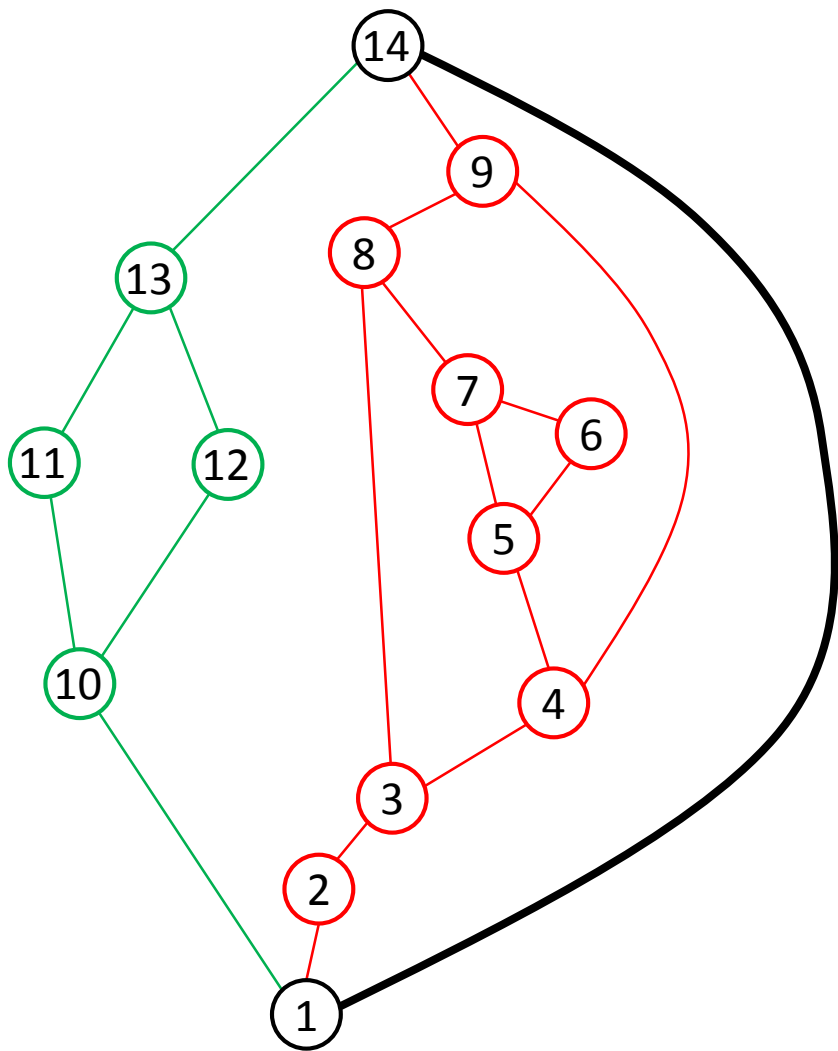


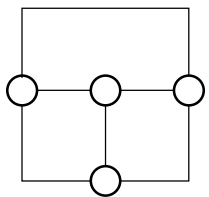
Changing the embedding



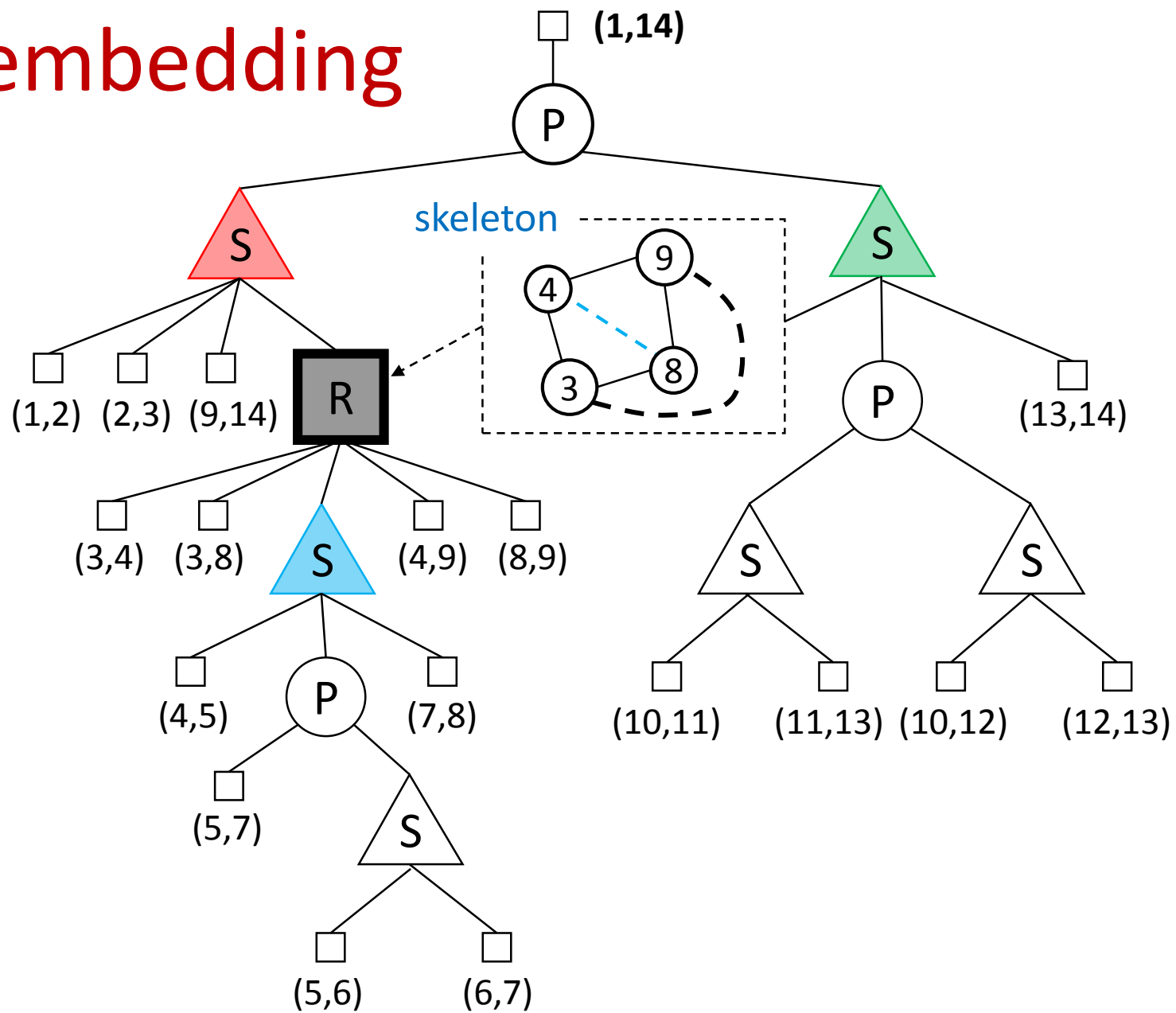
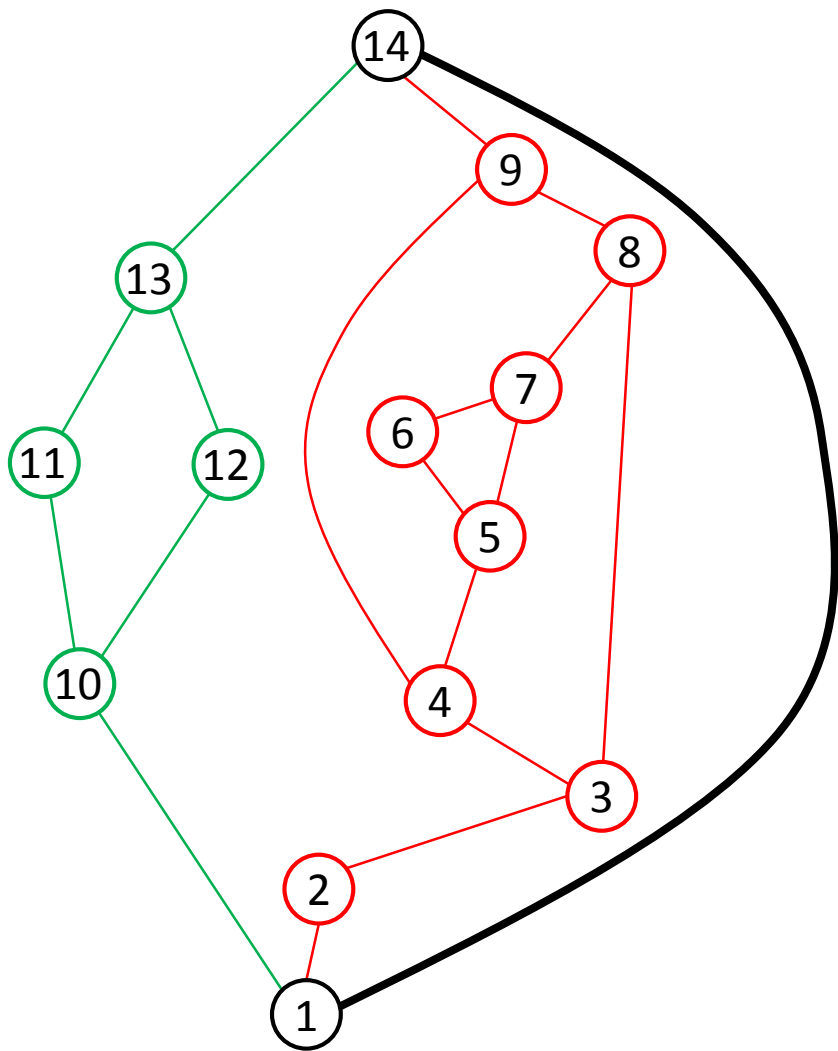


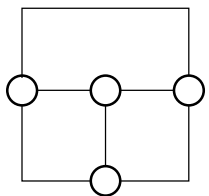
Changing the embedding



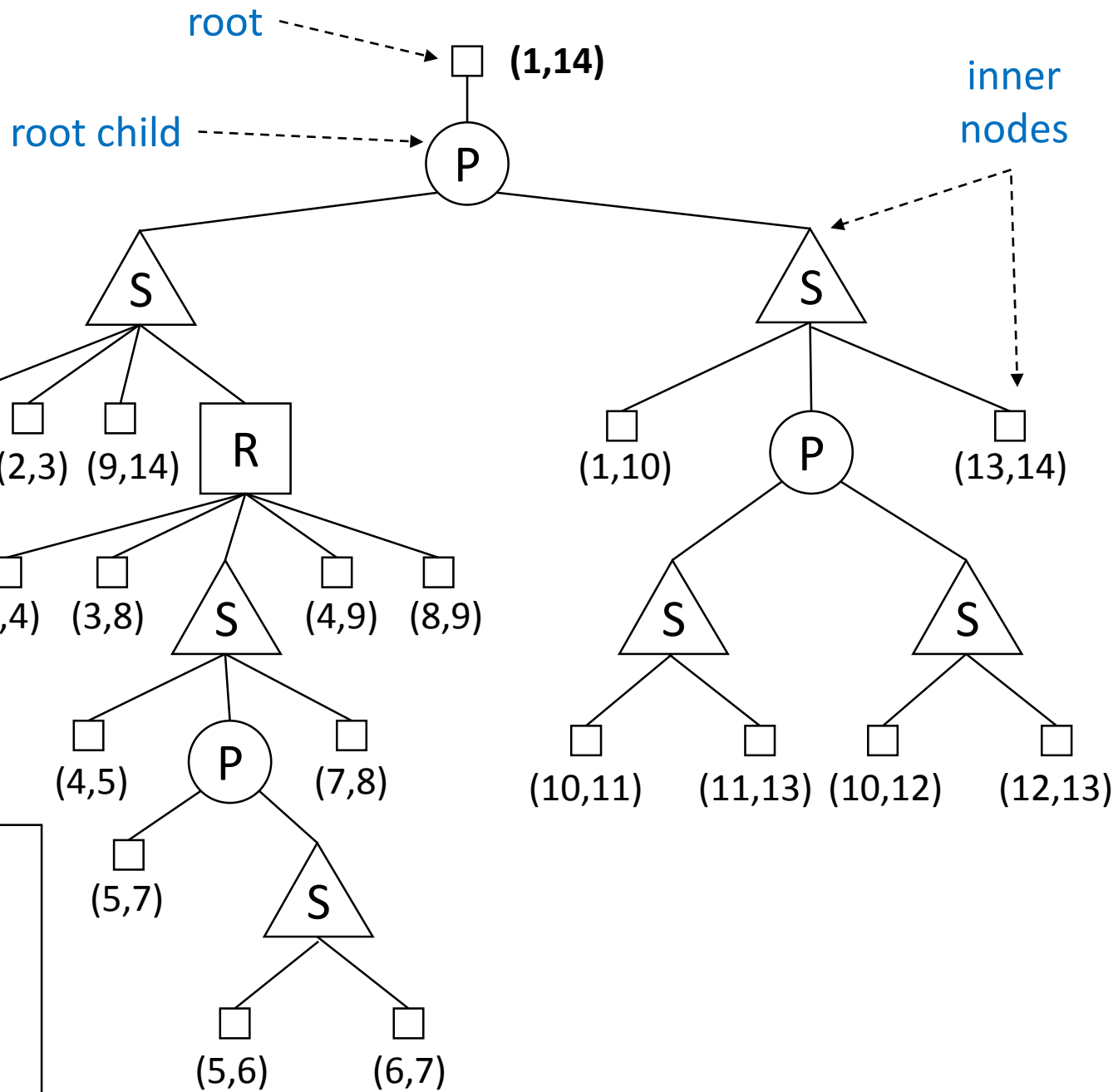
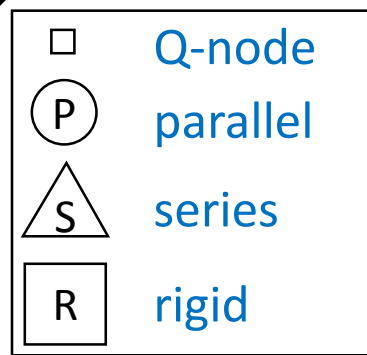
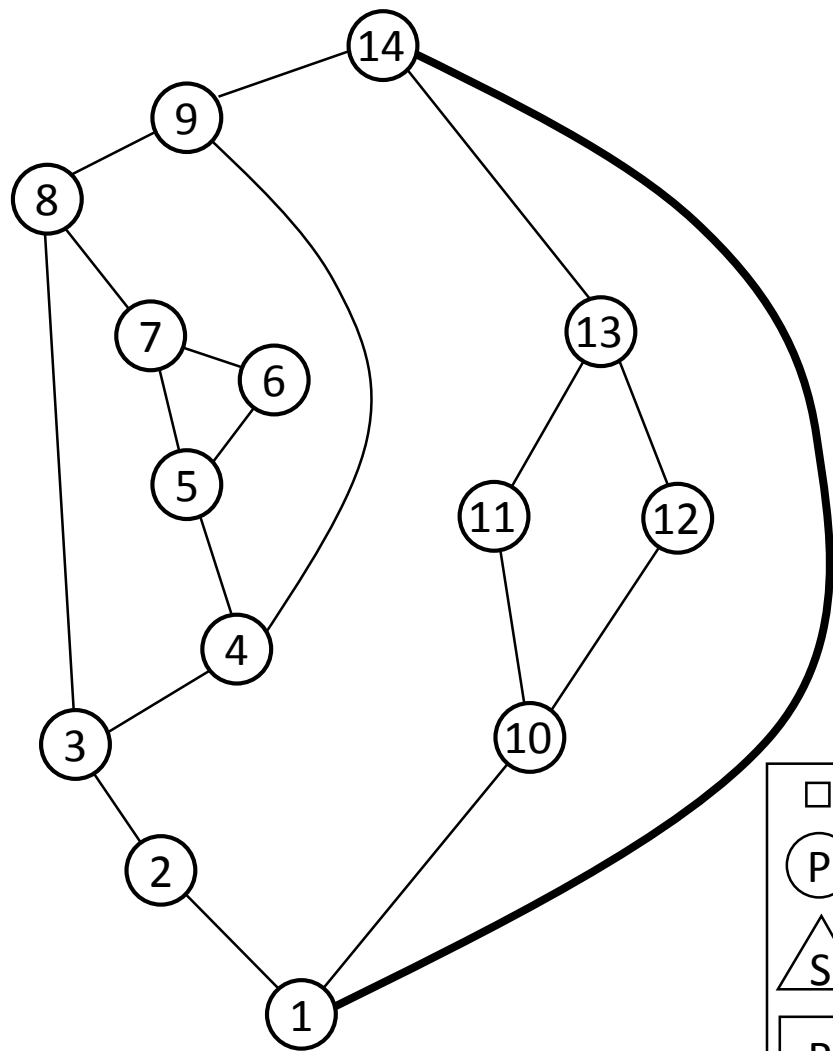


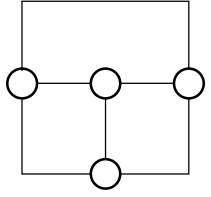
Changing the embedding



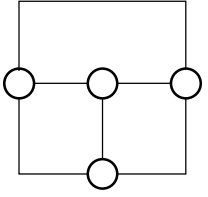


SPQR-trees





`\end{SPQR-trees}`

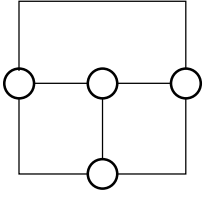


Orthogonal representations

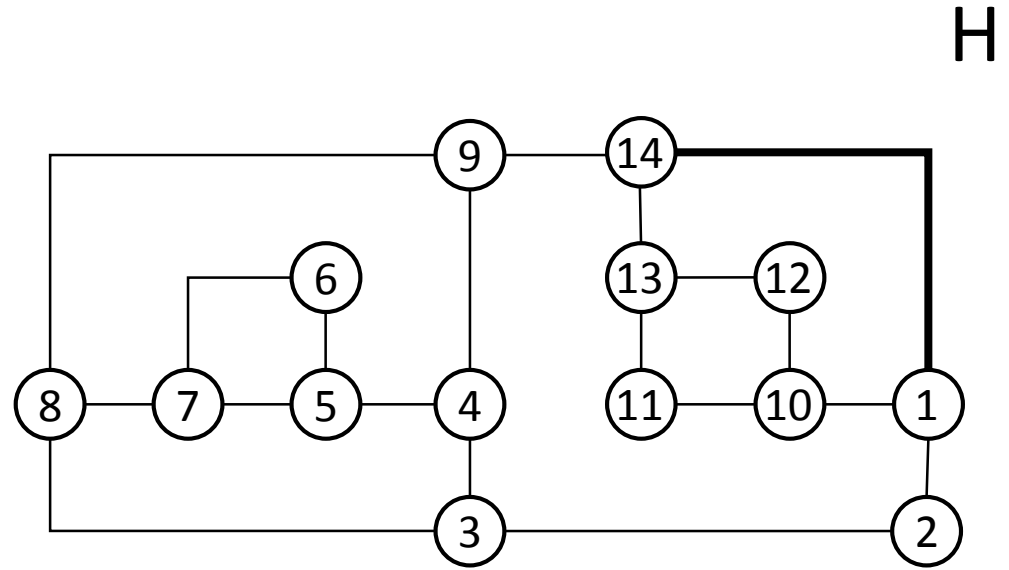
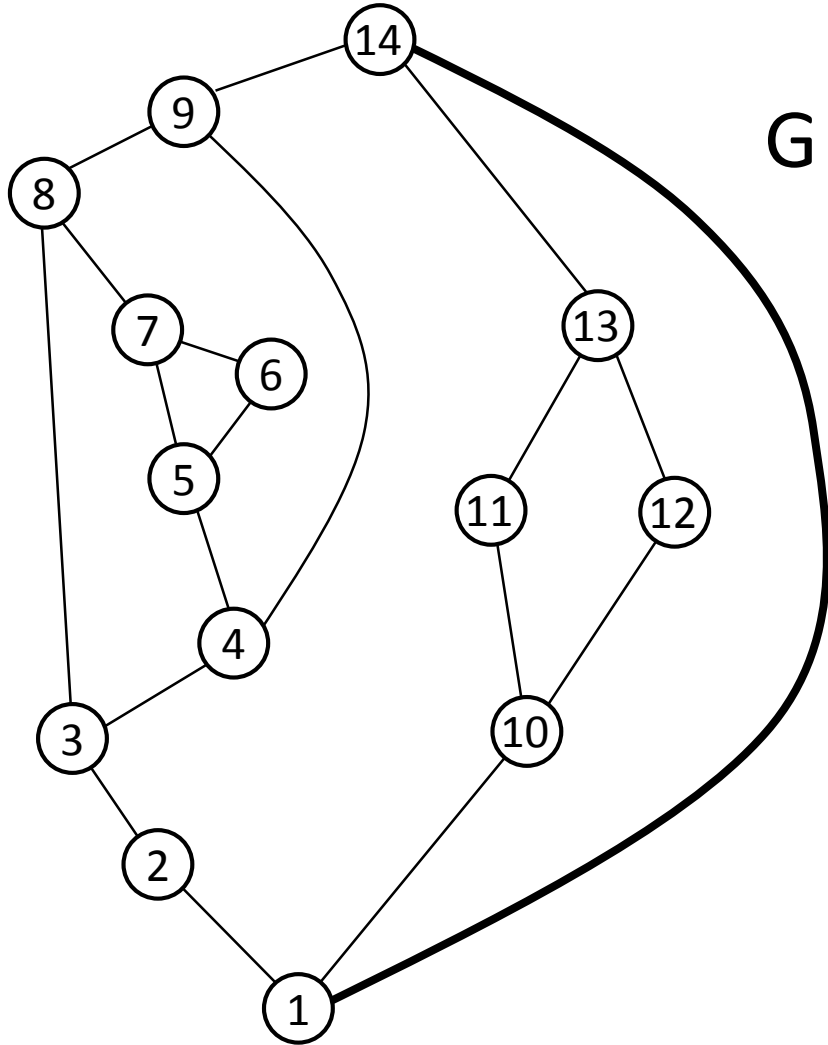
orthogonal representation = equivalence class of orthogonal drawings with the same vertex angles and the same sequence of bends along the edges

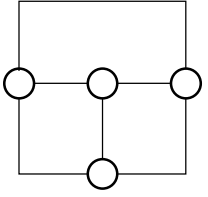
- a drawing of an orthogonal representation can be computed in linear time [Tamassia '97]

orthogonal component = orthogonal representation H_μ of a component G_μ

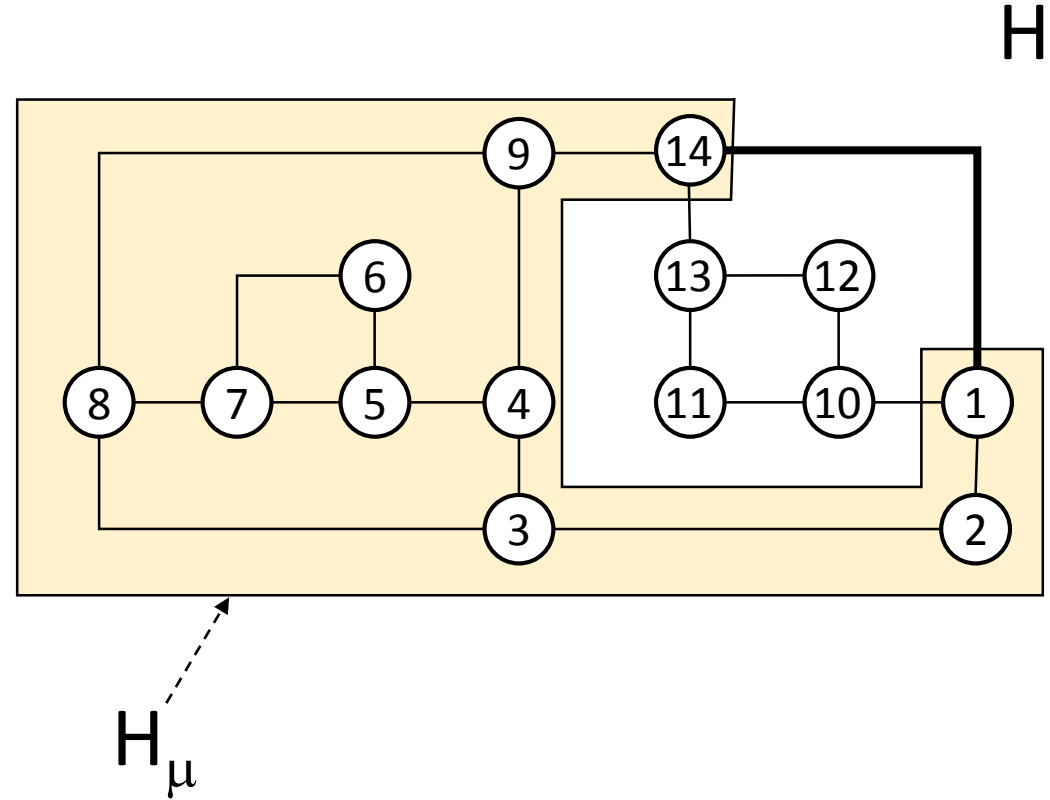
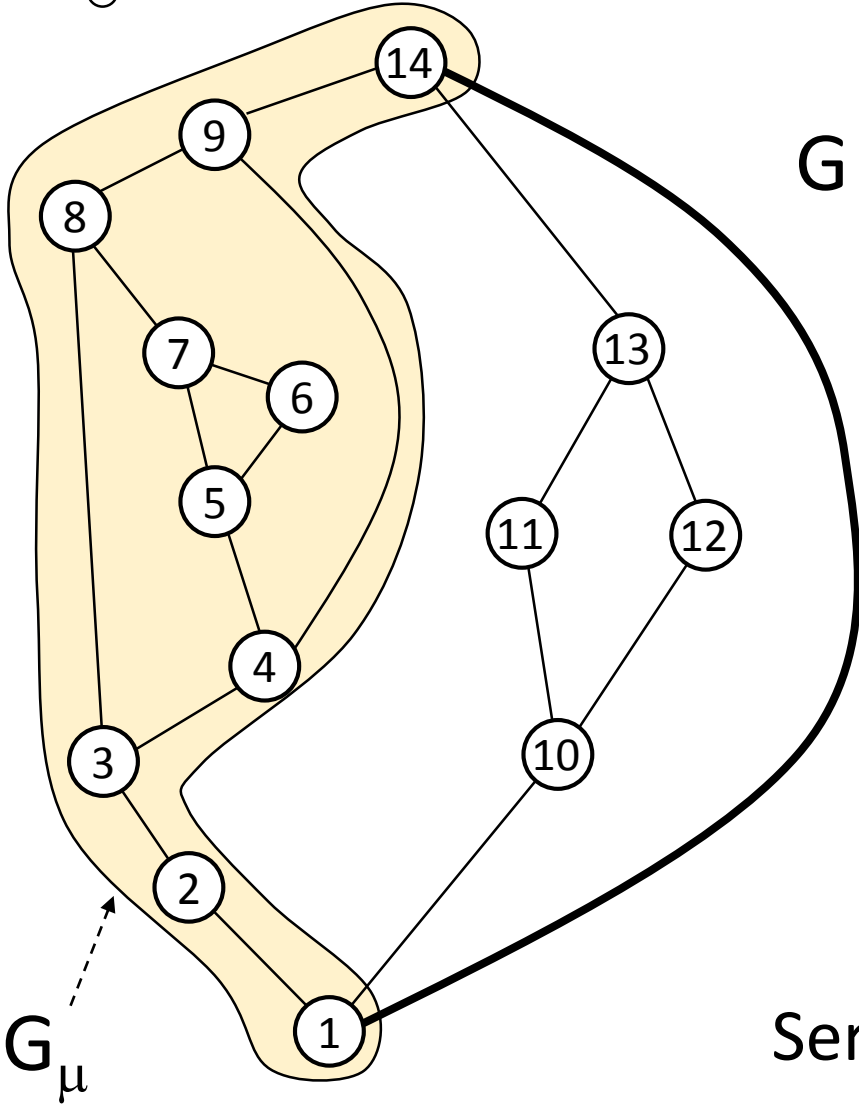


Orthogonal components: example

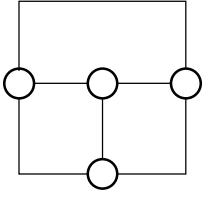




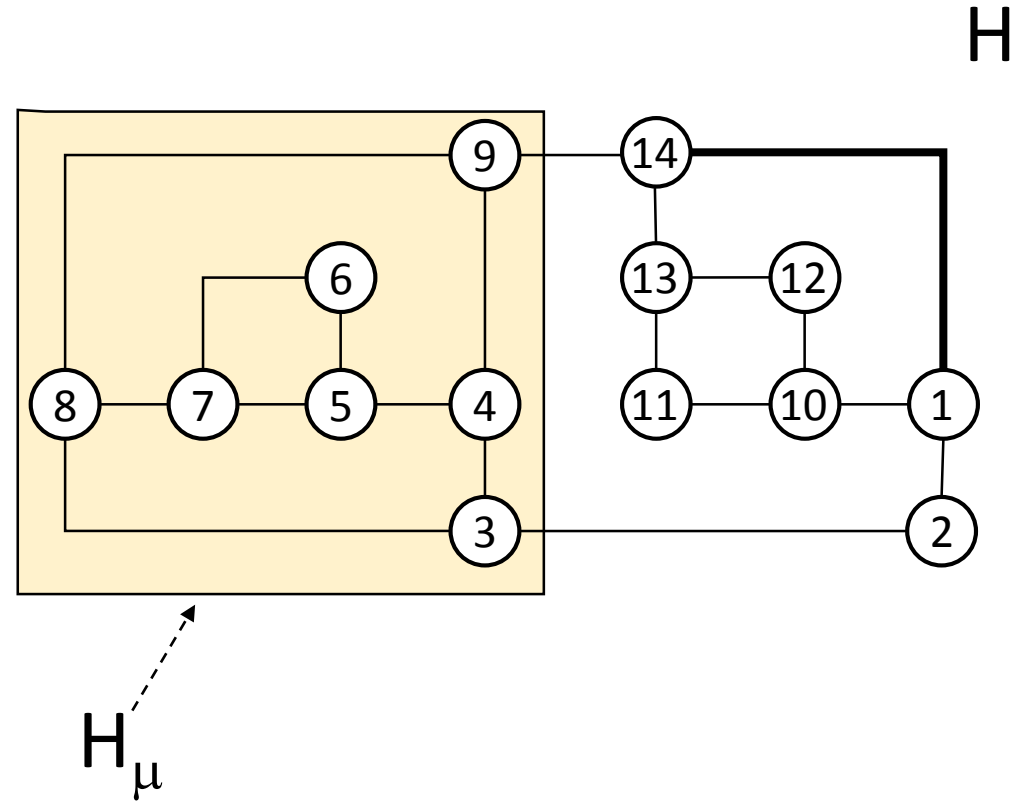
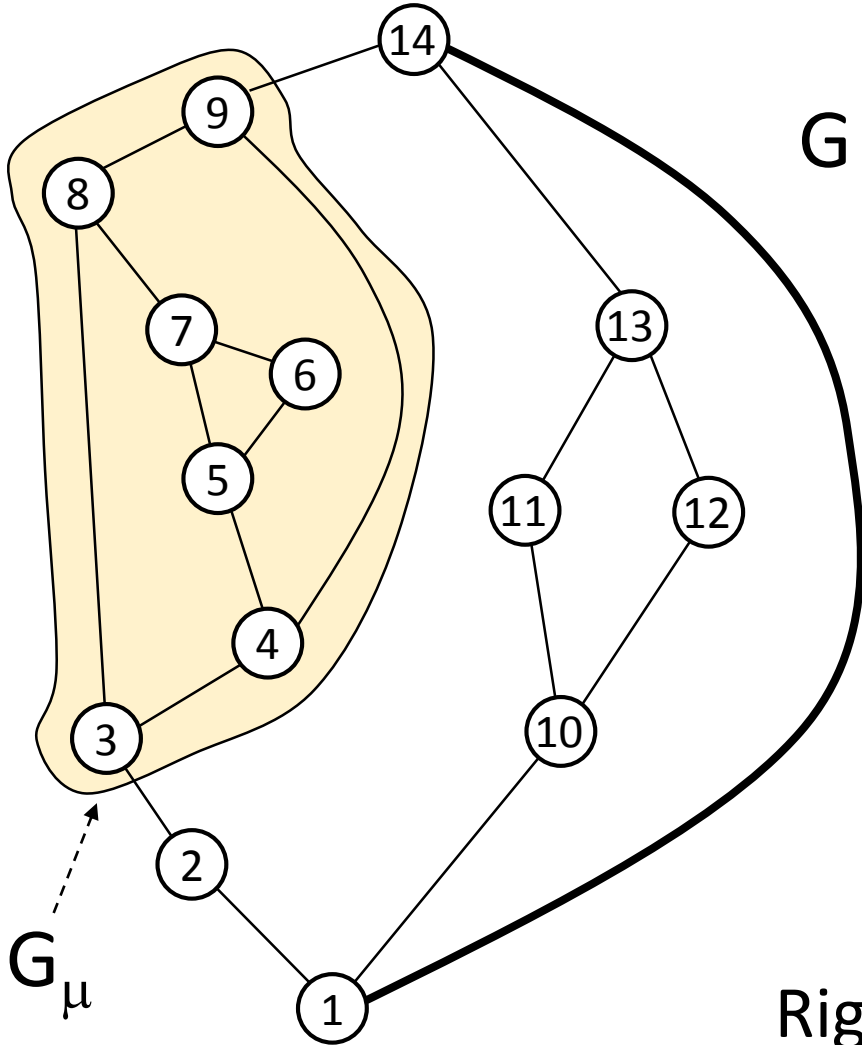
Orthogonal components: examples



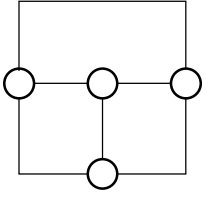
Series (orthogonal) component



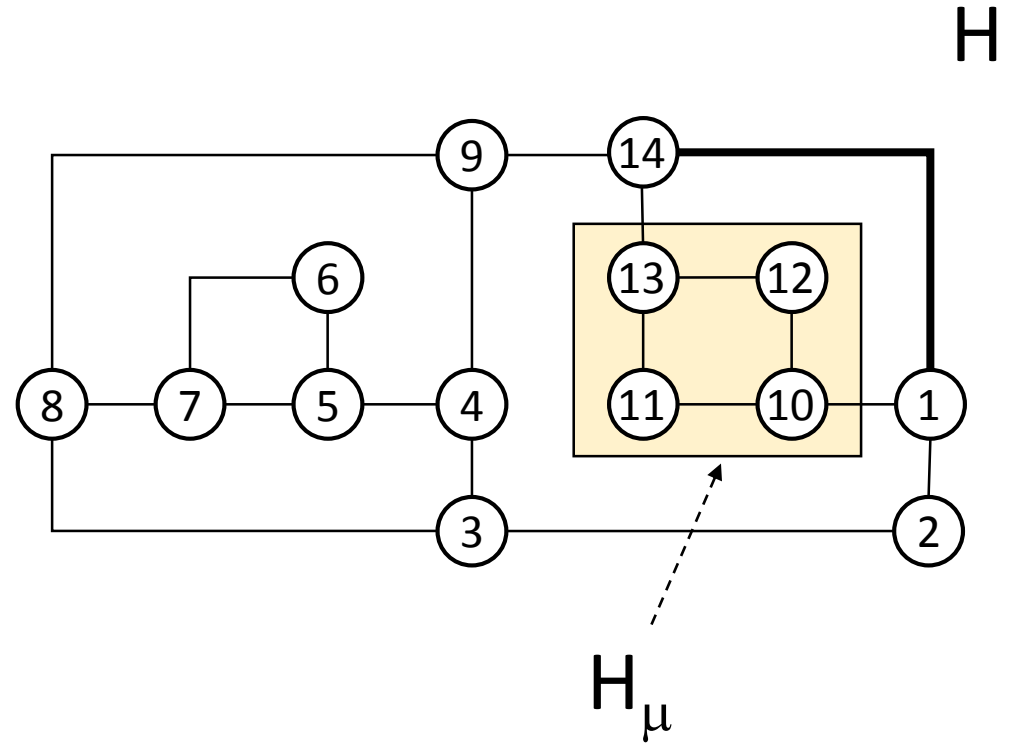
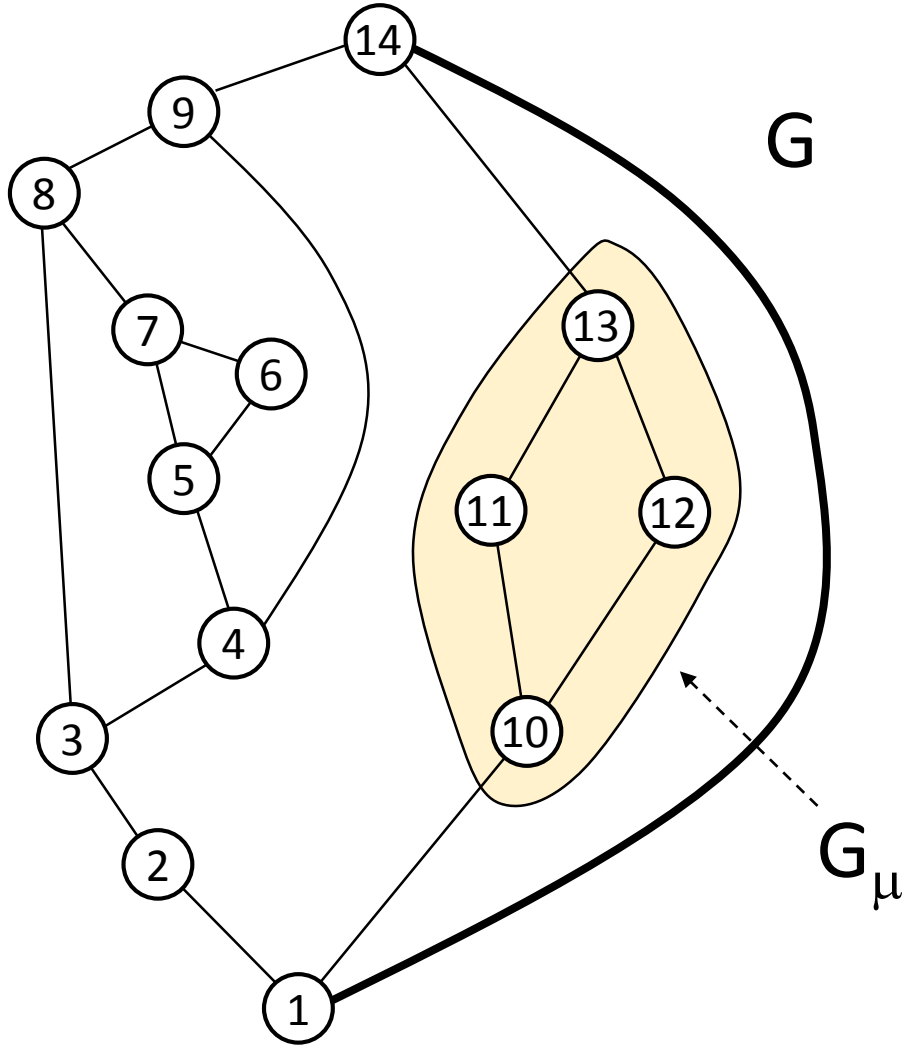
Orthogonal components: examples



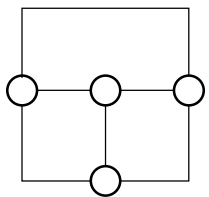
Rigid (orthogonal) component



Orthogonal components: examples

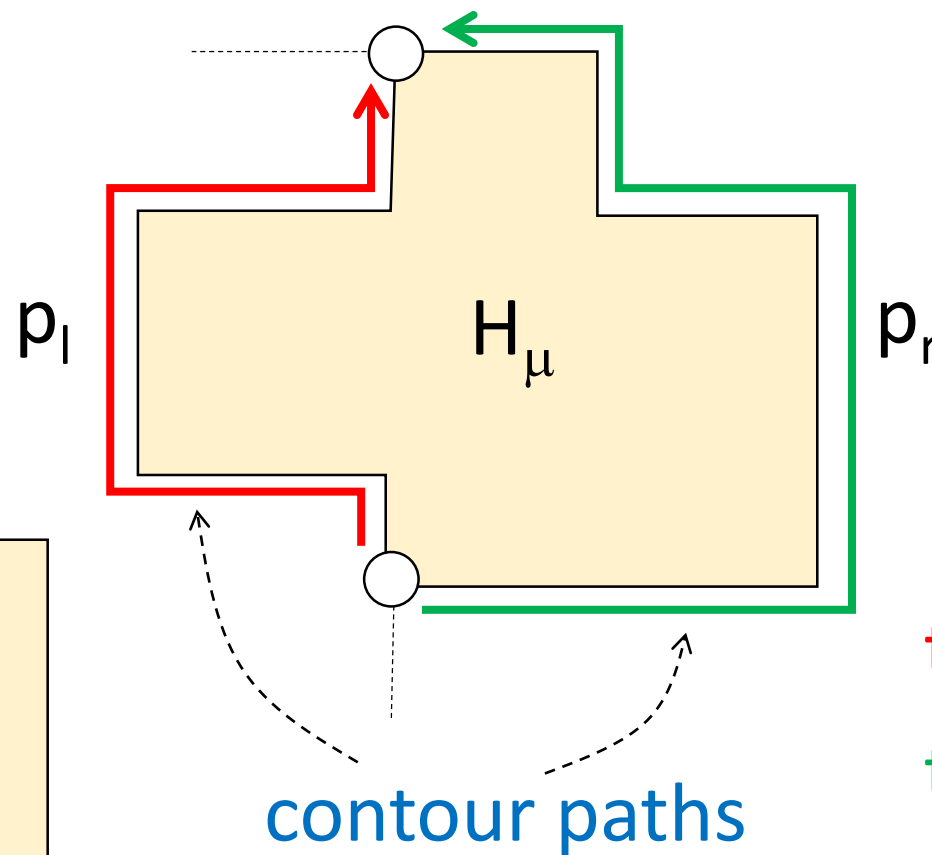
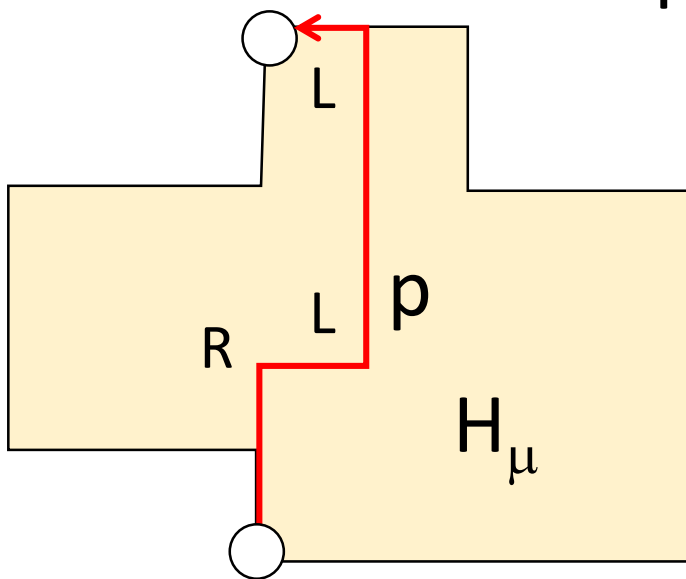
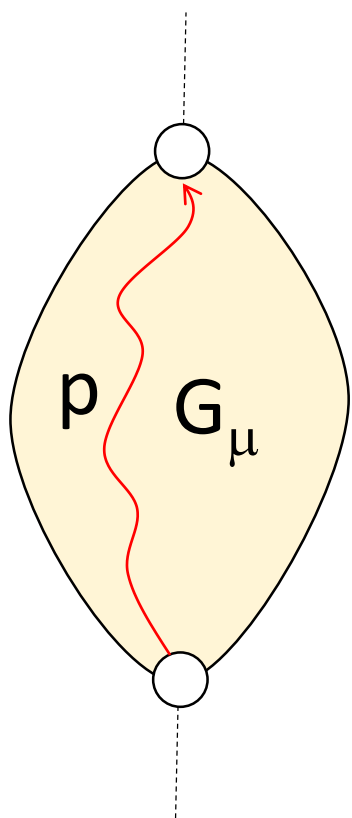


Parallel (orthogonal) component



Turn number and contour paths

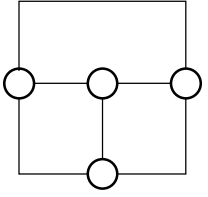
μ = node of the SPQR-tree



$$t(p_l) = 0$$

$$t(p_r) = 2$$

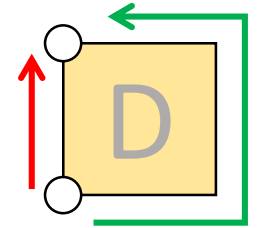
$$t(p) = \text{turn number} = |\# \text{left turns} - \# \text{right turns}| \text{ (along } p \text{)}$$



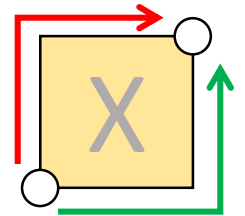
P- and R-components: shapes

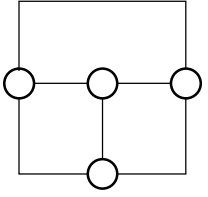
$\mu = \text{P-node or R-node}$

H_μ is **D-shaped** $\Leftrightarrow t(p_l) = 0$ and $t(p_r) = 2$ or vice versa



H_μ is **X-shaped** $\Leftrightarrow t(p_l) = t(p_r) = 1$

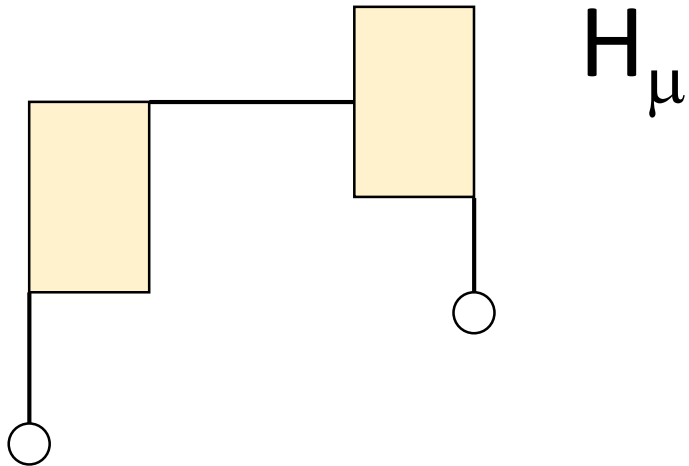


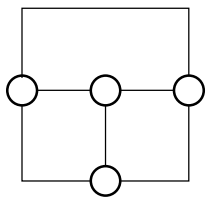


Inner S-components: spirality

μ = inner S-node

Lemma. All paths between the poles of an orthogonal component H_μ have the same turn number

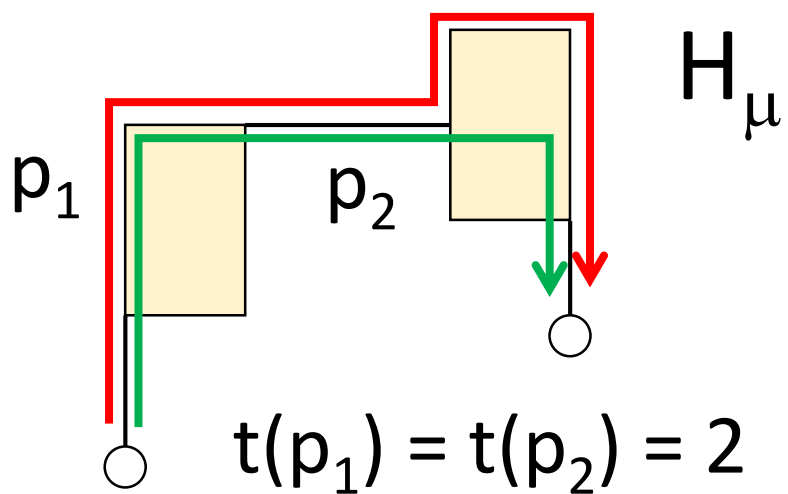




Inner S-components: spirality

μ = inner S-node

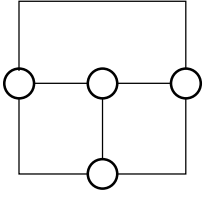
Lemma. All paths between the poles of a H_μ have the same turn number



$$t(p) = k$$

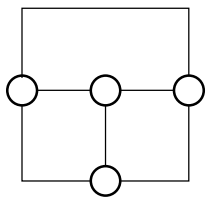
H_μ is k -spiral

H_μ has spirality k



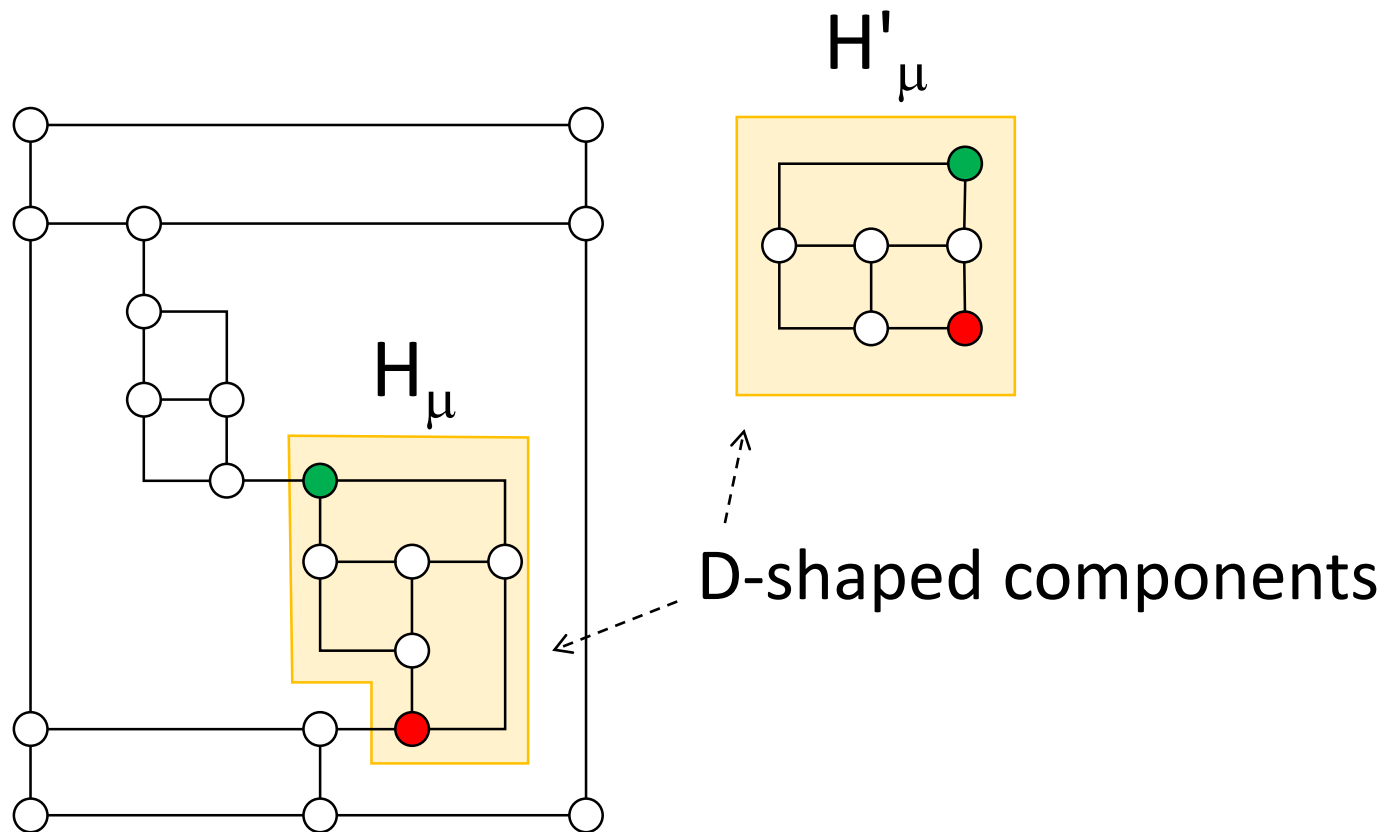
Equivalent orthogonal components

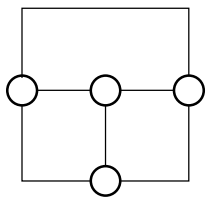
- H_μ and H'_μ = two distinct orthogonal representations of G_μ
- H_μ and H'_μ are **equivalent** if:
 - μ is a P- or an R-node and H_μ, H'_μ are both D-shaped or both X-shaped
 - μ is an S-node and H_μ, H'_μ have the same spirality



Equivalent orthogonal components

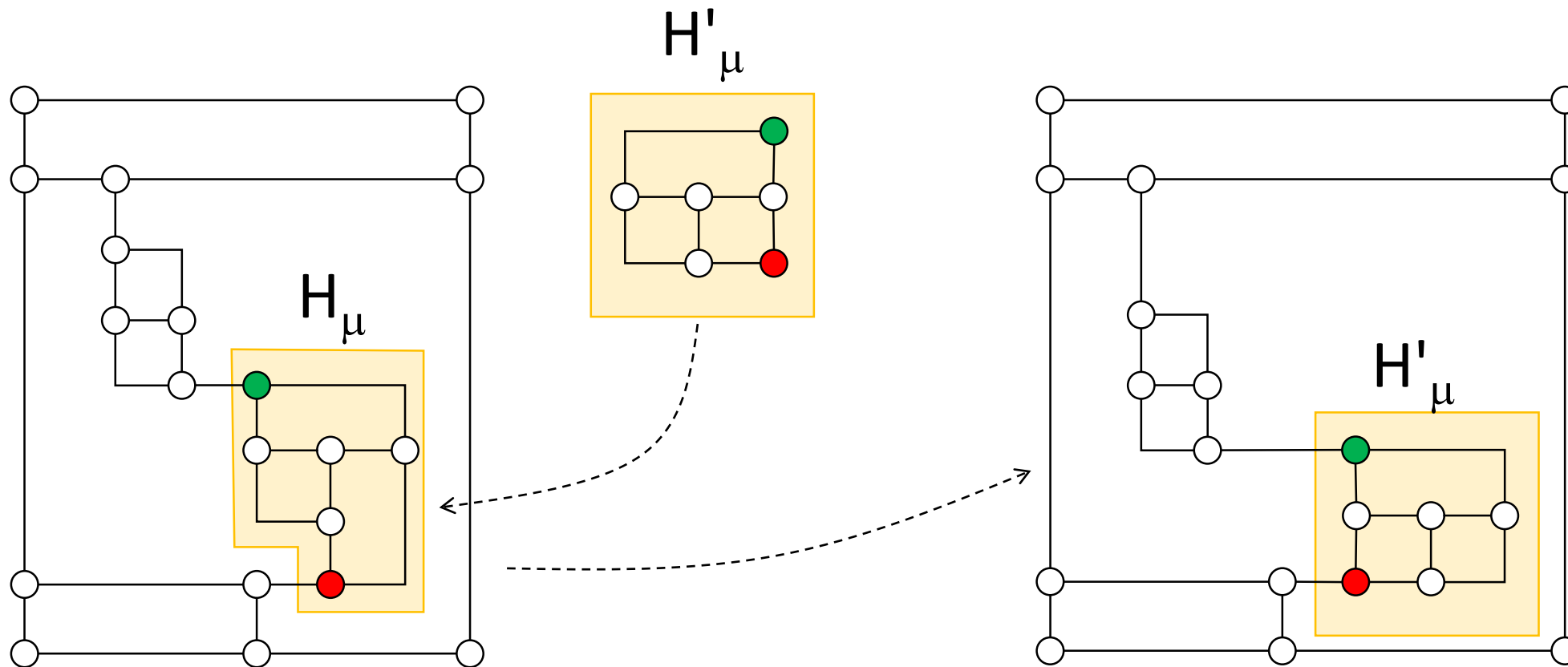
Theorem (substitution). Equivalent orthogonal components are interchangeable

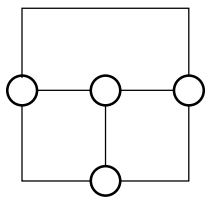




Equivalent orthogonal components

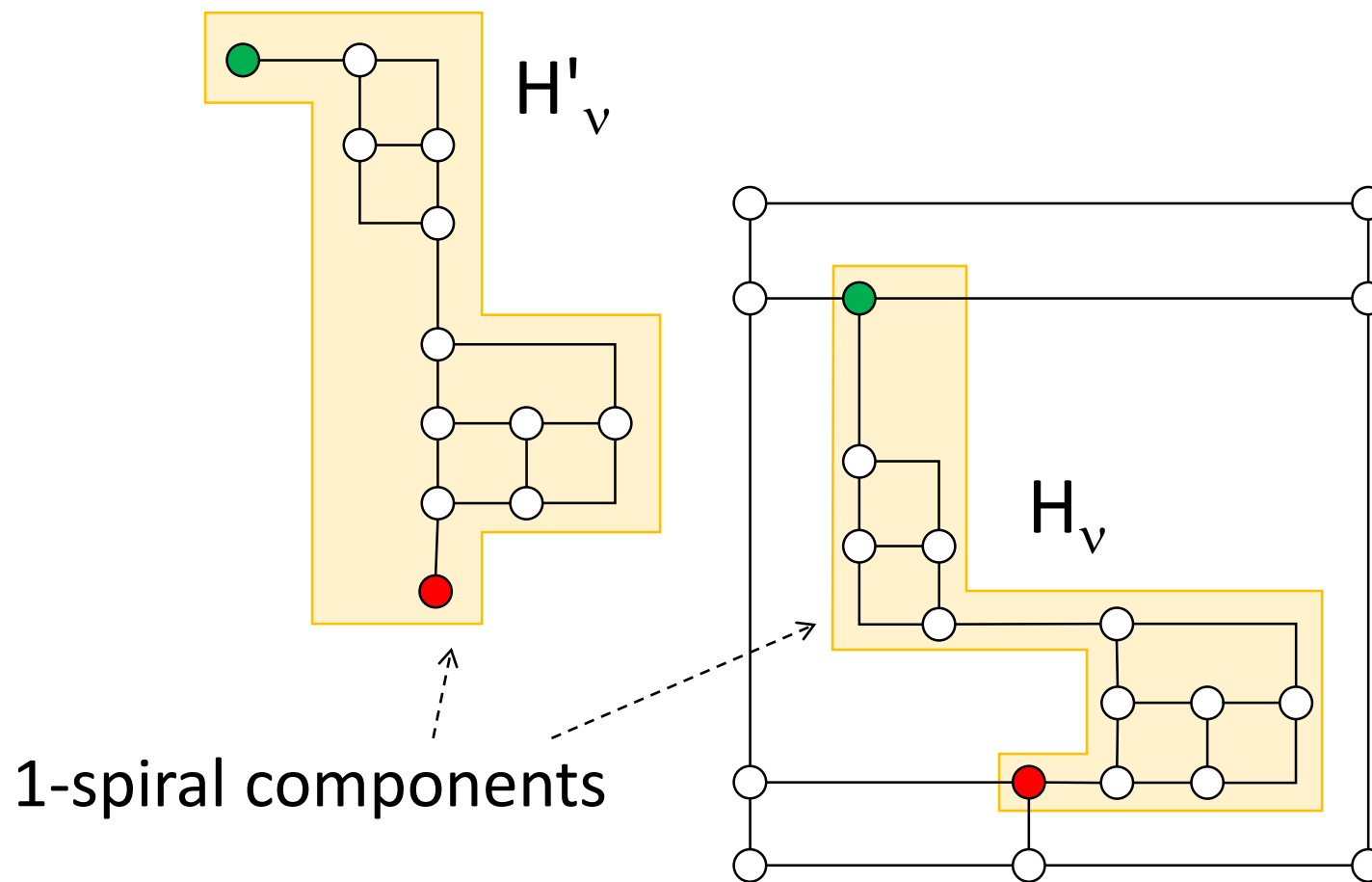
Theorem (substitution). Equivalent orthogonal components are interchangeable

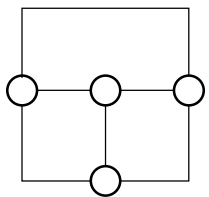




Equivalent orthogonal components

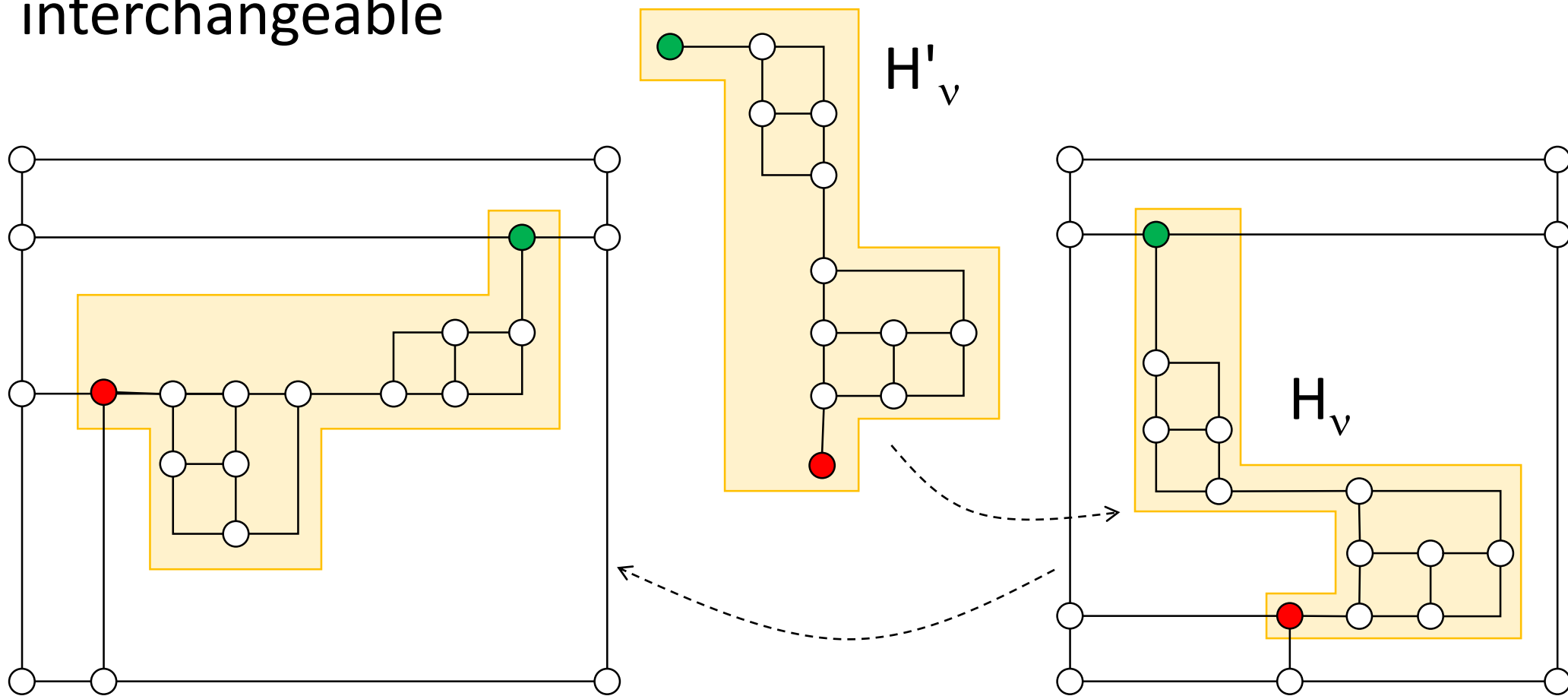
Theorem (substitution). Equivalent orthogonal components are interchangeable

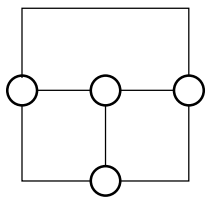




Equivalent orthogonal components

Theorem (substitution). Equivalent orthogonal components are interchangeable

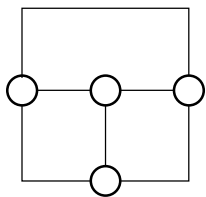




Key lemma

Key-Lemma. Every biconnected planar 3-graph with a given edge e admits a bend-min orthogonal representation with e on the external face such that:

- 01.** every edge has at most two bends
- 02.** every inner P- or R-component is D- or X-shaped
- 03.** every inner S-component has spirality at most 4

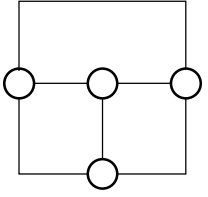


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proof: based on a characterization of no-bend orthogonal representations [Rahman, Nishizeki, Naznin 2003]

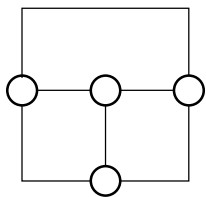


Key lemma: consequence

Key-Lemma. Every biconnected planar 3-graph with a given edge e admits a bend-min orthogonal representation with e on the external face such that:

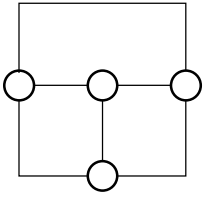
- O1.** every edge has at most two bends
- O2.** every inner P- or R-component is D- or X-shaped
- O3.** every inner S-component has spirality at most 4

Consequence: we can restrict our algorithm to search for a bend-min representation that satisfies O1, O2, and O3.



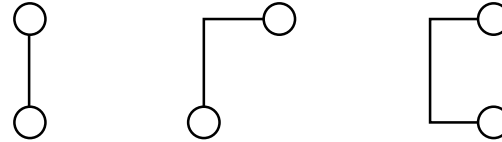
Algorithm

- **input:** biconnected planar 3-graph G with a reference edge e
 - **output:** bend-min representation H of G with e on the external face
1. compute the SPQR-tree T of G with respect to e
 2. visit the nodes μ of T bottom-up:
 - **μ inner node** \Rightarrow store in μ a set of candidate bend-min representations of G_μ – one for each distinct equivalence class, thanks to the substitution theorem
 - **μ the root child** \Rightarrow construct H by suitably merging e with the candidate representations stored at the children of μ ; consider $\{0, 1, 2\}$ bends for e , thanks to O1 of the key-lemma

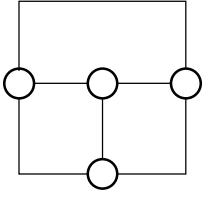


Candidate sets of inner nodes

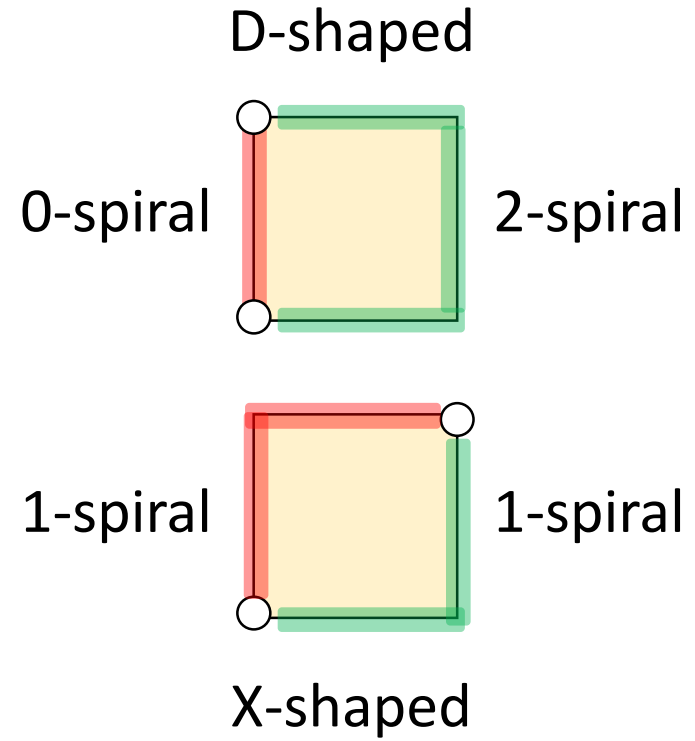
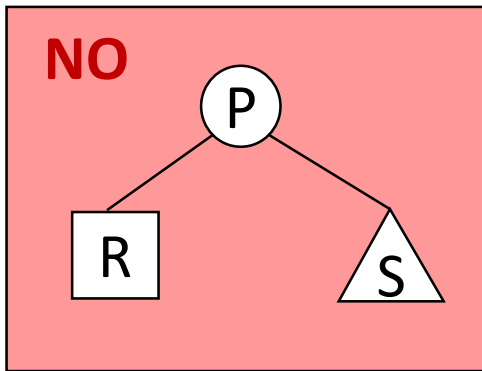
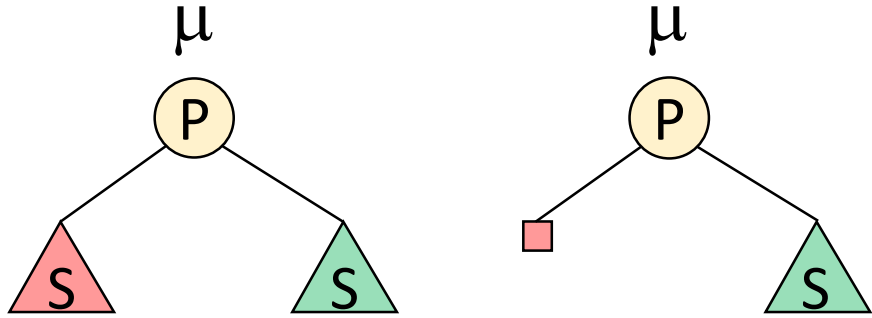
- **Q-node:** a representation for each number of bends in $\{0, 1, 2\}$
– thanks to O1 of the key-lemma



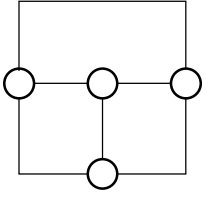
- **P/R-node:** the cheapest D-shaped and the cheapest X-shaped representations
– thanks to O2 of the key-lemma
- **S-node:** the cheapest representation for each value of spirality in $\{0, 1, 2, 3, 4\}$
– thanks to O3 of the key-lemma



Candidate set of an inner P-node

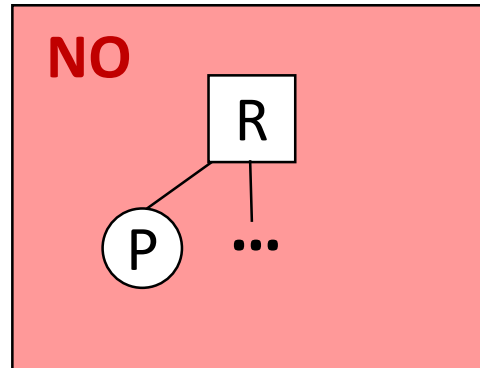
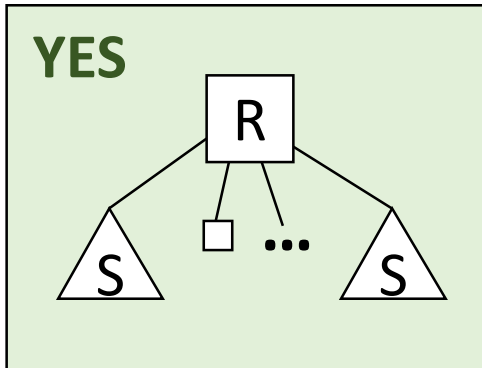


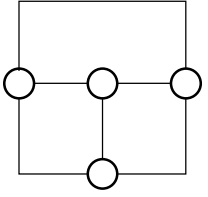
O(1) time



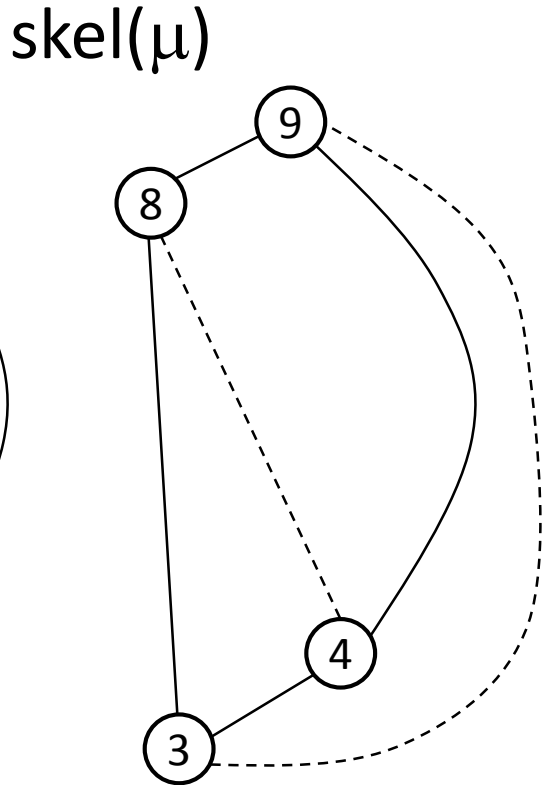
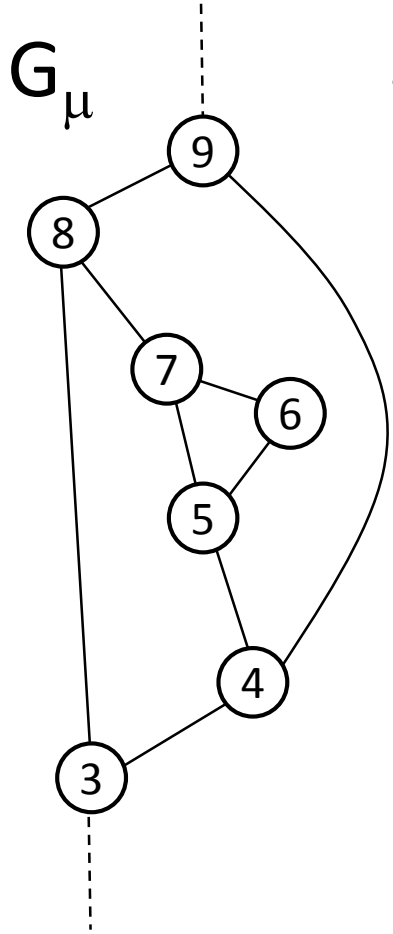
Candidate set of an inner R-node

Each child of an R-node is either a Q- or an S-node

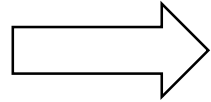




Candidate set of an inner R-node

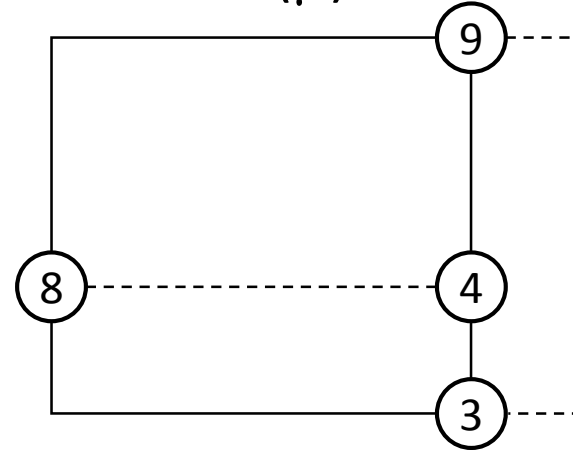


$O(n)$ -time
variant of
[RNN'99]

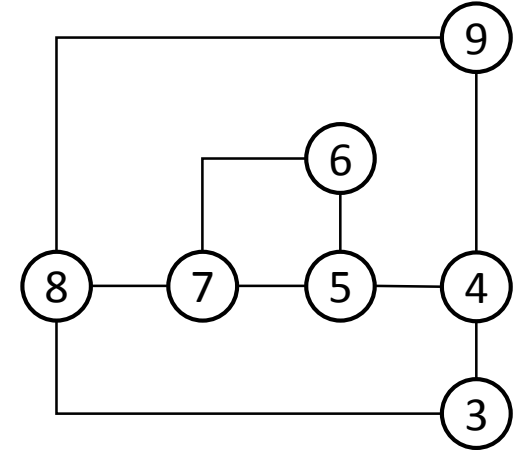


min-bend
3-connected
cubic (with
constraints)

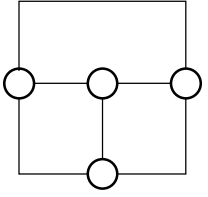
constrained
min-bend of
skel(μ)



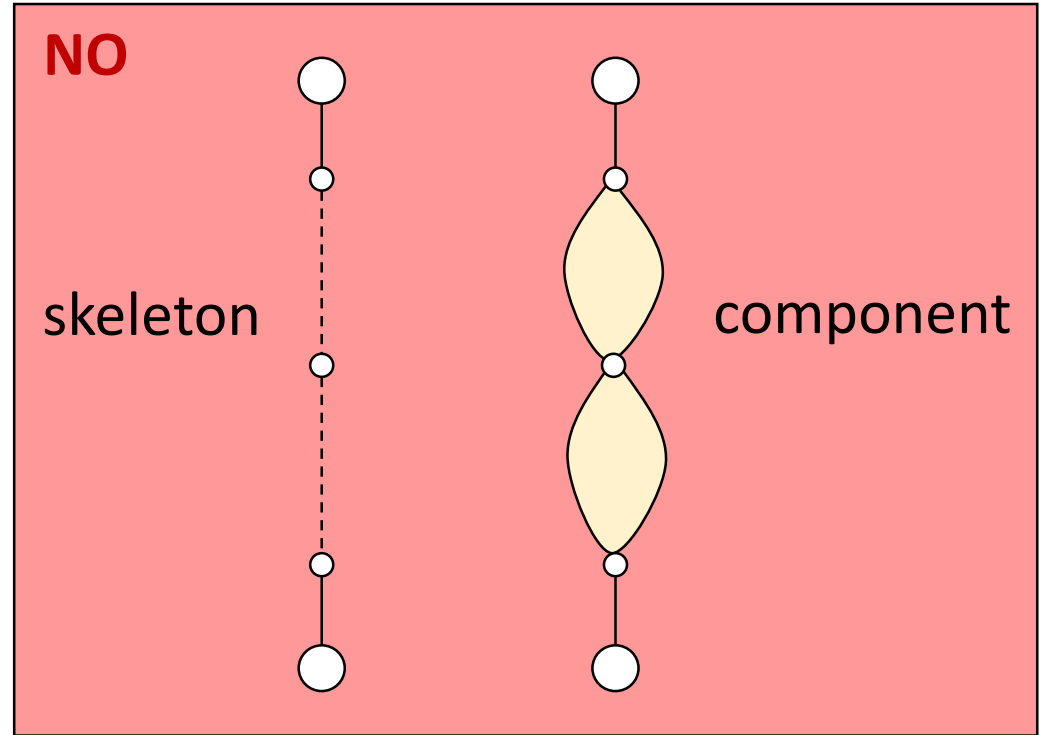
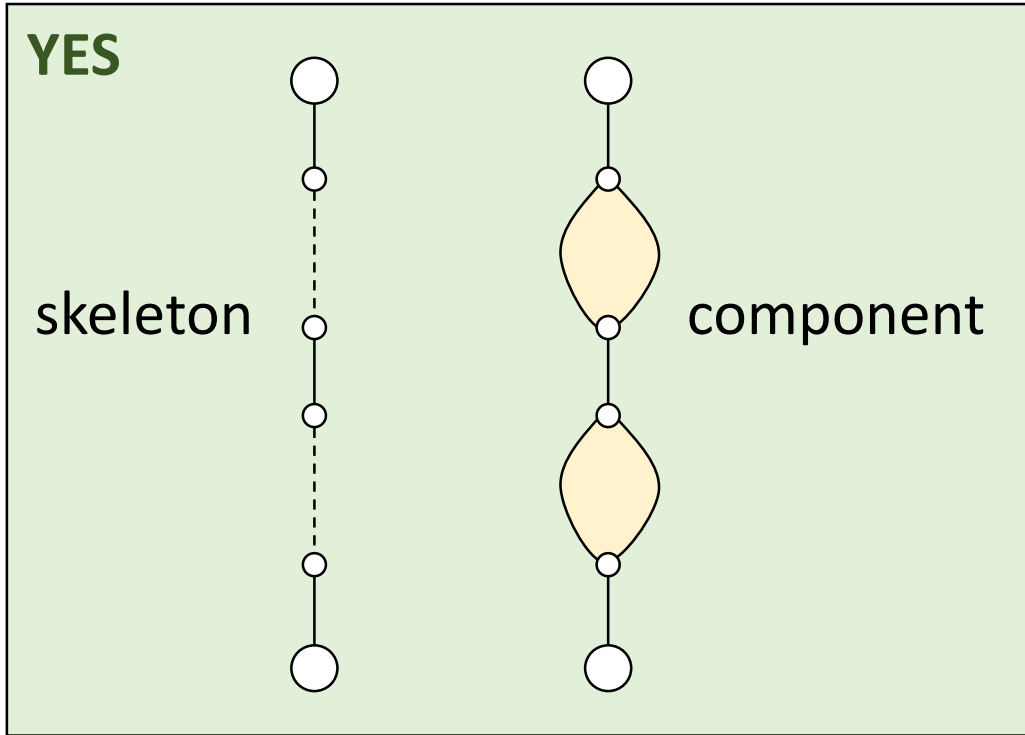
min-bend
D-shaped

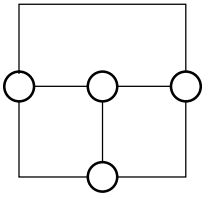


$O(n_\mu)$ time

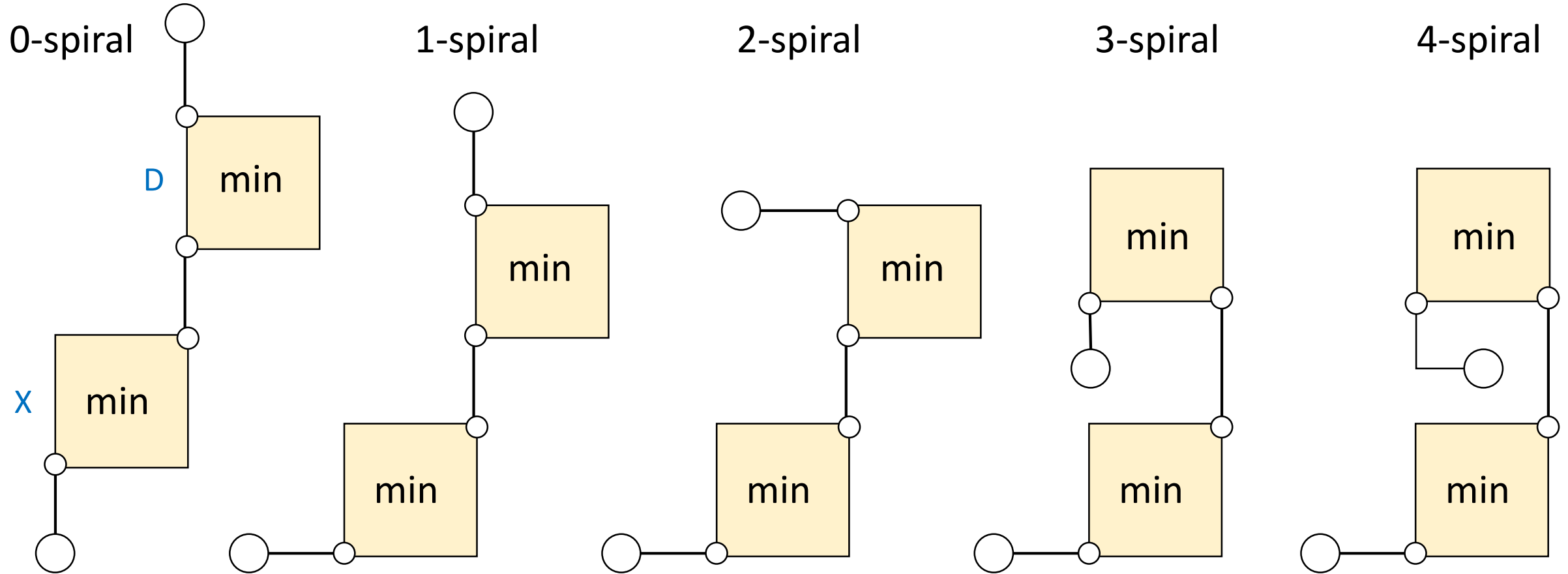


Candidate set of an inner S-node



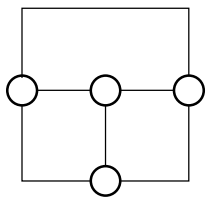


Candidate set of an inner S-node



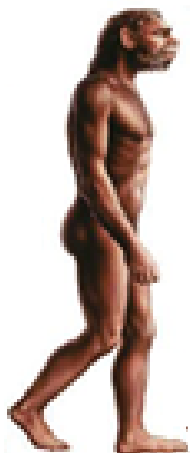
$\#(\text{extra bends}) = \max\{0, \text{spirality} - (\#D\text{-shaped} + \#Q\text{-nodes} - 1)\}$

$O(n_\mu)$ time

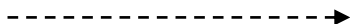


Open problems

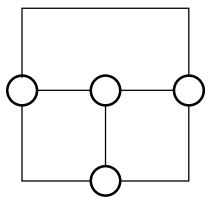
- **Problem 1.** Is there a subquadratic-time algorithm to compute a bend-minimum orthogonal drawing of a planar 3-graph?



$O(n^2)$
our result



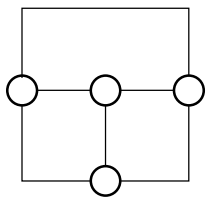
Can we do
better?



Open problems: even more prehistoric

- **Problem 2.** Is there a linear-time algorithm to compute a bend-minimum orthogonal drawing of a plane 4-graph (in the *fixed embedding setting*)?





Thank you!

Giuseppe
Liotta



3



Maurizio
Patrignani

